Communication Protocol

EtherCAT®

for the Trigon™ family

Trigon™ BAG552

Bayard-Alpert SingleGauge

Trigon™ BPG552

Bayard-Alpert Pirani DualGauge

Trigon™ BCG552

Bayard Alpert Pirani Capacitance Diaphragm TripleGauge®

Table of Contents

General Information 5
Intended Use 5
EtherCAT–Interface 5
Validity 5
Trademarks 5

1 Technical Data 6

2 Interface Connection 7

3 Operation 8
3.1 Introduction 8
3.2 Front View 8
3.3 Indicators and Switches 9
3.3.1 <RUN> LED 9
3.3.2 <ERR> LED 9
3.3.3 <LA> LED (<IN> Port) 9
3.3.4 <LA> LED (<OUT> Port) 9
3.3.5 Device Address Switch 10

4 BAG552: Object Structure 11
4.1 Object Dictionary structure 11
4.2 Communication Profile Objects (0x1000…0x1FFF) 12
4.2.1 Process Data Objects (PDO's) 12
4.3 Input Area (0x6000…0x6FFF) 13
4.3.1 Input Common Hot Cathode Ion 13
4.3.2 Input Hot Cathode Ion 14
4.3.3 Input Trip Point 1 14
4.3.4 Input Trip Point 2 14
4.4 Configuration Area (0x8000…0x8FFF) 15
4.4.1 Configuration Hot Cathode Ion 15
4.4.2 Configuration Trip Point 1 15
4.4.3 Configuration Trip Point 2 17
4.5 Information Area (0x9000…0x9FFF) 18
4.5.1 Information Hot Cathode Ion 18
4.5.2 Information Trip Point 1/2 19
4.6 Device Area (0xF000...0xAFFF) 19
4.6.1 Semiconductor Device Profile 19
4.6.2 Module Profile List 19
4.6.3 Exceptions 19
4.6.4 Active Exception Status 19
4.6.5 Active Device Warning Details 20
4.6.6 Active Device Error Details 20
4.6.7 Active Global Device Warning Details 20
4.6.8 Active Global Device Error Details 21
4.6.9 Latched Device Warning Details 21
4.6.10 Latched Device Error Details 21
4.6.11 Latched Global Device Warning Details 22
4.6.12 Latched Global Device Error Details 22
4.6.13 Device Warning Mask 22
4.6.14 Device Error Mask 22
4.6.15 Global Device Warning Mask 22
4.6.16 Global Device Error Mask 23
4.6.17 Trip Point Output All 23
4.6.18 Input Latch Local Timestamp 23
4.6.19 Configure Device 23
4.6.20 Information Device 24
4.6.21 Command Degas ON / OFF 24
4.6.22 Command Emission ON / OFF 25
4.6.23 Device Reset Command 26
4.6.24 Exception Reset Command 26
4.6.25 Store Parameters Command 27
4.6.26 Calculate Checksum Command 28
4.6.27 Load Parameters Command 28

5 BPG552: Object Structure 30
5.1 Object Dictionary structure 30
5.2 Communication Profile Objects (0x1000…0x1FFF) 31
5.2.1 Process Data Objects (PDO's) 31

5.3 Input Area (0x6000…0x6FFF) 33
5.3.1 Input Common Heat Transfer 33
5.3.2 Input Heat Transfer 33
5.3.3 Input Common Hot Cathode Ion 33
5.3.4 Input Hot Cathode Ion 34
5.3.5 Input Trip Point 1 34
5.3.6 Input Trip Point 2 34
5.4 Configuration Area (0x8000…0x8FFF) 35
5.4.1 Configuration Hot Cathode Ion 35
5.4.2 Configuration Trip Point 1 35
5.4.3 Configuration Trip Point 2 37
5.5 Information Area (0x9000…0x9FFF) 38
5.5.1 Information Heat Transfer 38
5.5.2 Information Hot Cathode Ion 38
5.5.3 Information Trip Point 1/2 39
5.6 Device Area (0xF000...0xAFFF) 39
5.6.1 Semiconductor Device Profile 39
5.6.2 Module Profile List 39
5.6.3 Exceptions 40
5.6.4 Active Exception Status 40
5.6.5 Active Device Warning Details 40
5.6.6 Active Device Error Details 40
5.6.7 Active Global Device Warning Details 41
5.6.8 Active Global Device Error Details 41
5.6.9 Latched Device Warning Details 42
5.6.10 Latched Device Error Details 42
5.6.11 Latched Global Device Warning Details 43
5.6.12 Latched Global Device Error Details 43
5.6.13 Device Warning Mask 43
5.6.14 Device Error Mask 43
5.6.15 Global Device Warning Mask 44
5.6.16 Global Device Error Mask 44
5.6.17 Combination Gauge 44
5.6.18 Trip Point Output All 45
5.6.19 Input Latch Local Timestamp 45
5.6.20 Configure Device 45
5.6.21 Information Device 46
5.6.22 Command Zero Adjust 46
5.6.23 Command Full Scale Adjust 47
5.6.24 Command Degas ON / OFF 48
5.6.25 Command Emission ON / OFF 48
5.6.26 Device Reset Command 49
5.6.27 Exception Reset Command 50
5.6.28 Store Parameters Command 50
5.6.29 Calculate Checksum Command 51
5.6.30 Load Parameters Command 52

6 BCG552: Object Structure 54
6.1 Object Dictionary structure 54
6.2 Communication Profile Objects (0x1000…0x1FFF) 55
6.2.1 Process Data Objects (PDO's) 55
6.3 Input Area (0x6000…0x6FFF) 57
6.3.1 Input Common Capacitance Diaphragm 57
6.3.2 Input Capacitance Diaphragm 57
6.3.3 Input Common Piezo 57
6.3.4 Input Piezo 58
6.3.5 Input Common Heat Transfer 58
6.3.6 Input Heat Transfer 58
6.3.7 Input Common Hot Cathode Ion 59
6.3.8 Input Hot Cathode Ion 59
6.3.9 Input Trip Point 1 60
6.3.10 Input Trip Point 2 60
6.4 Configuration Area (0x8000…0x8FFF) 60
6.4.1 Configuration Hot Cathode Ion 60
6.4.2 Configuration Trip Point 1 61
6.4.3 Configuration Trip Point 2 63
6.5 Information Area (0x9000…0x9FFF) 64
6.5.1 Information Capacitance Diaphragm 64
6.5.2 Information Piezo 65
6.5.3 Information Heat Transfer 65
6.5.4 Information Hot Cathode Ion 65
6.5.5 Information Trip Point 1/2 65

6.6 Device Area (0xF000...0xAFFF) 66
6.6.1 Semiconductor Device Profile 66
6.6.2 Module Profile List 66
6.6.3 Exceptions 66
6.6.4 Active Exception Status 66
6.6.5 Active Device Warning Details 67
6.6.6 Active Device Error Details 68
6.6.7 Active Global Device Warning Details 69
6.6.8 Active Global Device Error Details 69
6.6.9 Latched Device Warning Details 70
6.6.10 Latched Device Error Details 71
6.6.11 Latched Global Device Warning Details 71
6.6.12 Latched Global Device Error Details 72
6.6.13 Device Warning Mask 72
6.6.14 Device Error Mask 72
6.6.15 Global Device Warning Mask 73
6.6.16 Global Device Error Mask 73
6.6.17 Combination Gauge 73
6.6.18 Trip Point Output All 74
6.6.19 Input Latch Local Timestamp 74
6.6.20 Configure Device 75
6.6.21 Information Device 76
6.6.22 Command Zero Adjust 77
6.6.23 Command Full Scale Adjust 77
6.6.24 Command Degas ON / OFF 78
6.6.25 Command Emission ON / OFF 79
6.6.26 Device Reset Command 79
6.6.27 Exception Reset Command 80
6.6.28 Store Parameters Command 81
6.6.29 Calculate Checksum Command 82
6.6.30 Load Parameters Command 83

Appendix **84**
A: Overview Setting Trip Points 84
B: Examples Setting Trip Points 86
C: Literature 89

For cross-references within this document, the symbol (→ 🗎 XY) is used, for cross-references to further documents, listed under literature, the symbol (→ 🕮 [Z]).

General Information

Caution

Data transmission errors

Any attempt to simultaneously operate the gauge via the RS232C Serial Interface and EtherCAT interface or the diagnostic port may result in incorrect data and data transmission errors.

Therefore, it is inadmissible to simultaneously operate the gauge via the RS232C Serial Interface and EtherCAT interface, or the diagnostic port.

The terminology in this document corresponds to the EtherCAT standardization. For historical reasons, other INFICON product-specific documents (e.g. operating manuals) use the term "setpoint" instead of "trip point".

Intended Use

This Communication Protocol contains instructions for operating EtherCAT interfaces (slaves) together with a master.

For safety information, specifications and operation instructions of the vacuum gauges refer to the appropriate documents:

BAG552 → 🕮 [1]
BPG552 → 🕮 [2]
BCG552 → 🕮 [3]

EtherCAT–Interface

The following description of the EtherCAT interface is compliant to the EtherCAT specification of the EtherCAT Technology Group (ETG) and to the 🕮 "EtherCAT Semiconductor Device Profile".

This manual describes the functionality of a EtherCAT slave and supports

- ETG.5003.1 S (R) V1.1.0: Part 1 Common Device Profile (CDP) (→ 🕮 [12]) and
- ETG.5003.2080 S (R) V1.3.0: Part 2080: Specific Device Profile (SDP): Vacuum Pressure Gauge (→ 🕮 [13]).

For operating the gauge via EtherCAT, prior installation of the device specific ESI file is required on the bus master side. This file can be downloaded from the respective product page:

- ESI file for BAG552: www.inficon.com
- ESI file for BPG552: www.inficon.com
- ESI file for BCG552: www.inficon.com

Validity

This manual is based on firmware version 1.0.0.
If your unit does not work as described in this document, please check that it is equipped with the above firmware version:

- BAG552 (→ 🗎 12, Index 100A)
- BPG552 (→ 🗎 31, Index 100A)
- BCG552 (→ 🗎 55, Index 100A)

Trademarks

Trigon™	INFICON Holding AG
TripleGauge®	INFICON Holding AG
EtherCAT®	EtherCAT® is a registered trademark and patented technology, licensed by Beckhoff Automation GmbH, Germany.

1 Technical Data

For further technical data, see the respective operating manual in the "Literature" chapter, 🗎 89.

EtherCAT interface

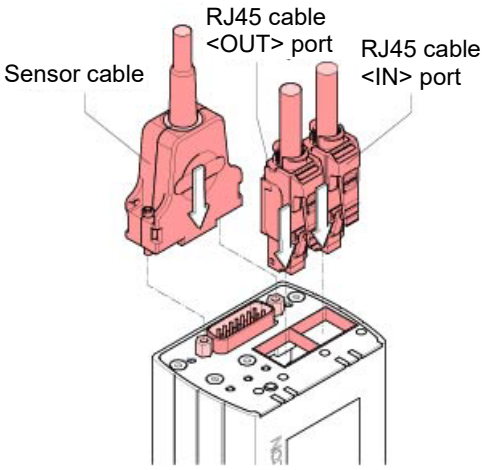
Communication protocol	protocol specialized for EtherCAT
Communication standards	ETG.5003.1: Part 1 Common Device Profile (CDP) ETG.5003.2080: Part 2080 Specific Device Profile (SDP): Vacuum Pressure Gauge
Data rate	100 Mbps
Node address	Explicit Device Identification
Physical layer	100BASE-Tx (IEEE 802.3)
EtherCAT connector	2 × RJ45, 8-pin (socket) <IN>: EtherCAT input <OUT> EtherCAT output
Cable	shielded, special Ethernet Patch Cable (CAT5e quality or higher)
Cable length	≤100 m
Process data	Fixed PDO mapping and configurable PDO mapping
Mailbox (CoE)	SDO requests, responses and information

2 Interface Connection

For operating the BxG55x gauge via EtherCAT, an Ethernet Patch Cable (CAT5e quality) with RJ45 connector is required.

The device supports daisy-chained operation:

- The previous device or EtherCAT Controller has to be connected to the BxG55x <IN> port.
- Optionally, the cable from the BxG55x <OUT> port has to be connected to the next EtherCAT device.



3 Operation

3.1 Introduction

Via the EtherCAT interface, the following and further data are exchanged in the standardized EtherCAT protocol:

- Pressure reading
- Pressure unit (Torr, mbar, Pa)
- Status and error messages
- Status of the switching functions
- Set Trip Point for switching functions

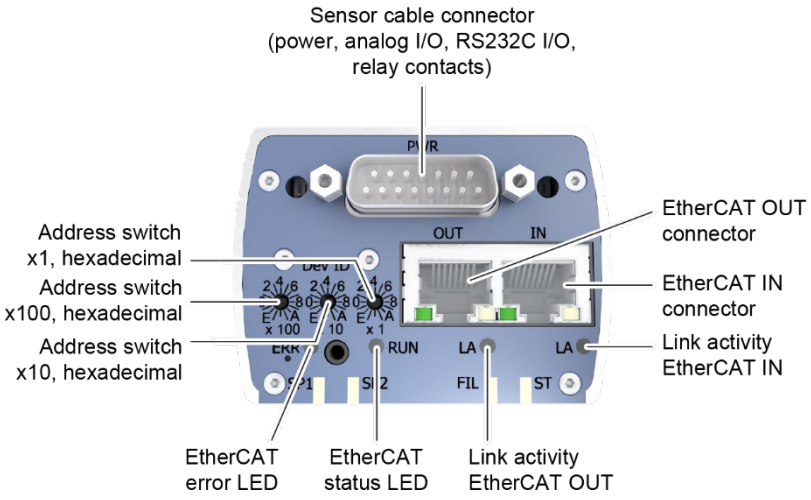
Caution

Data transmission errors

Any attempt to simultaneously operate the gauge via the RS232C Serial Interface and EtherCAT interface or the diagnostic port may result in incorrect data and data transmission errors.

Therefore, it is inadmissible to simultaneously operate the gauge via the RS232C Serial Interface and EtherCAT interface or the diagnostic port.

3.2 Front View



3.3 Indicators and Switches

3.3.1 <RUN> LED

Displays the operating status.

RUN

Color	LED State	Description
green	off	INIT (initialization status) or no power applied to device.
	blinking (200 ms on 200 ms off)	PREOP (pre-operational status).
	single flash (200 ms on 1000 ms off)	SAFEOP (safe-operational status). Communication of cyclic data transfer running. Input values available, output values written to the device but not updated on device output.
	on	OP (operational status).

3.3.2 <ERR> LED

Displays the error content.

ERR

Color	LED State	Description
red	off	No error or no power applied to device.
	blinking (200 ms on 200 ms off)	Error occurred (see error parameter).
	single flash (200 ms on 1000 ms off)	Slave device application has changed the EtherCAT state autonomously, due to local error (see error parameter).
	double flash (200 ms on 200 ms off 200 ms on 1000 ms off)	An application watchdog timeout has occurred. Sync Manager Watchdog timeout or communication timeout occurred.
	on	A critical communication or application controller error has occurred. Application controller is not responding any more (PDI Watchdog Timeout detected by ESC)

3.3.3 <LA> LED (<IN> Port)

Displays the input status.

LA

Color	LED State	Description
green	off	Port not connected or no power applied to device.
	blinking	Port connected and communication active.
	on	Port connected but no communication.

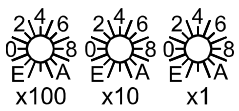
3.3.4 <LA> LED (<OUT> Port)

Displays the output status.

LA

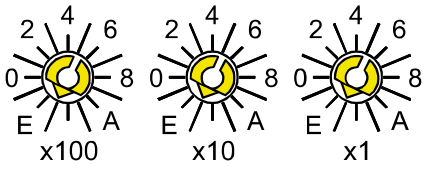
Color	LED State	Description
green	off	Port not connected or no power applied to device.
	blinking	Port connected and communication active.
	on	Port connected but no communication.

3.3.5 Device Address Switch



During device initialization, the device address switches are read by the device firmware. This device address is supported to the master as Explicit Device Identification.

Example: Value of the Explicit Device ID = 0xDDD (dec 3549):
0x100 * 0xD (dec 3328) + 0x10 * 0xD (dec 208) + 0x1 * 0xD (dec 13)



4 BAG552: Object Structure

This chapter describes the CANopen over EtherCAT (CoE) Object Dictionary.

4.1 Object Dictionary structure

The objects in the CoE Object Dictionary can be accessed with SDO services, and many of the dictionary objects can be mapped for cyclic communication in PDO's. Each object is addressed using a 16-bit index and an 8-bit subindex.

The following table presents the overall layout of the standard Object Dictionary.

Index (hex.)	Object dictionary area	
1000 – 1FFF	Communication profile area	
2000 – 5FFF	Manufacturer-specific profile area	
6000 – 6FFF	Profile Specific Area	Input area
7000 – 7FFF		Output area
8000 – 8FFF		Configuration area
9000 – 9FFF		Information area
A000 – AFFF		Diagnosis area
B000 – BFFF		Service Transfer area
C000 – EFFF		Reserved area
F000 – FFFF		Device area

Explanations for the abbreviations in the columns of the tables are given below:

Abbr.	Description
Access	SDO read/write access • RO: object can only be read by the SDO service • RW: object can be both read and written by the SDO service
CoE	CAN application protocol over EtherCAT
Index	Object Index (hex.) (address of an object)
NV	Nonvolatile; attribute value is maintained through power cycles
Object	Abstract representation of a particular component within a device, which consists of data, parameters, and methods.
PDO	Process Data Object. Structure described by mapping parameters containing one or several process data entities.
PM	PDO mapping • Rx: object can be mapped into an Rx PDO • Tx: object can be mapped into a Tx PDO
RxPDO	Receive PDO. A Process Data Object received by an EtherCAT slave.
SDO	Service Data Objects. CoE asynchronous mailbox communications where all objects in the Object Dictionary can be read and written.
SI	Subindex (hex.) (sub-address of an object)
Type	Data Type • BOOL, BIT = 1 bit. Boolean (0 = false, 1 = true) • USINT, BYTE = 8 bit. Unsigned Byte • UINT = 16 bit. Unsigned integer value • UDINT = 32 bit. Unsigned integer value • ULINT = 64 bit. Unsigned integer value • REAL = 32 bit. Floating point • V_STRING = 8×n bit. Visible string (1 byte for character) • O_STRING = 8xn bit. Octet string (1 byte for element)
TxPDO	Transmit PDO. A Process Data Object sent from an EtherCAT slave.

4.2 Communication Profile Objects (0x1000…0x1FFF)

The objects of the communication profile describe the basic EtherCAT properties of the BAG552 and are common to all EtherCAT slaves using the CoE communication protocol. The objects are described in following table:

Index	SI	DataType	NV	Access	PM	Name
1000		UDINT		RO		Device Type 0x0000138B => 0x138B = dec 5003
1008		V_STRING		RO		Manufacturer Device name
1009		V_STRING		RO		Manufacturer Hardware Version
100A		V_STRING		RO		Manufacturer Software Version
100B		V_STRING		RO		Manufacturer Bootloader Version
1018				RO		Identity Object
	0x01	UDINT		RO		Vendor ID
	0x02	UDINT		RO		Product Code
	0x03	UDINT		RO		Revision Number
	0x04	UDINT		RO		Serial Number
10F8		ULINT		RO		Timestamp Object

4.2.1 Process Data Objects (PDO's)

The BAG552 consists of one Bayard-Alpert Hot Ion vacuum pressure sensor. For each sensor module a default mapping is configured. The mapping for each sensor module has the same contents. For a compact cyclic data frame duplicated mappings can be deactivated.

Or to meet other requirements the TxPDO's 1A01 and the RxPDO 1601 are designated for user mapping. These PDO's do not have default values and can be set up by the PDO configuration.

RxPDO's

Index	SI	DataType	NV	Access	PM	Name
1600		PM		RW		RxPDO Receive PDO Mapping,
1601		PM		RW		RxPDO Receive PDO Mapping, User Mapping

TxPDO's

Index	SI	DataType	NV	Access	PM	Name
1A00		PM		RW		TxPDO Transmit PDO Mapping
	0x01	UDINT		RW		0x60050101 for Reading Valid
	0x02	UDINT		RW		0x60050201 for Overrange Exceeded
	0x03	UDINT		RW		0x60050301 for Underrange Exceeded
	0x04	UDINT		RW		0x00000005
	0x05	UDINT		RW		0x60001132 for Sensor Value
1A01		PM		RW		TxPDO Transmit PDO Mapping, User Mapping
1BFE		PM		RW		Transmit PDO Mapping
	0x01	UDINT		RW		0xF3800008 for Active Exception Status
	0x08	UDINT		RW		0xF6410132 for Trip Point Output All Instance
1BFF		PM		RW		TxPDO Transmit PDO Mapping Device, User Mapping
1C00	0x01 0x02 0x03 0x04	BYTE		RW		Sync Manager Type
1C12 / 1C13	0x01 0x02 0x03 0x04	UINT		RW		Sync Manager PDO Assignment
1C32 / 1C33	0x01 - 0x20			RW		Sync Manager Parameter

4.3 Input Area (0x6000…0x6FFF)

4.3.1 Input Common Hot Cathode Ion

Index	SI	DataType	NV	Access	PM	Name
6000	0x0E	BOOL		RO	tx	TxPdoState
	0x11	REAL		RO	tx	Sensor Value

Subindex 0x0E

Is set if the device is not in Safe State (value (I 0x6000, SI 0x11) = valid).

TxPdoState	
0	Invalid
1	Valid

Subindex 0x11

The corrected, converted, calibrated final analog input value of the sensor.

4.3.2 Input Hot Cathode Ion

Index	SI	DataType	NV	Access	PM	Name
6005	0x01	BOOL		RO	tx	Reading Valid
	0x02	BOOL		RO	tx	Overrange Exceeded
	0x03	BOOL		RO	tx	Underrange Exceeded
	0x05	BOOL		RO	tx	Emission Status Off/On
	0x06	BOOL		RO	tx	Degas Status Off/On

Subindex 0x01

Indicates whether the Value parameter contains a valid value within the specified accuracy or not.

Reading Valid	
0	Invalid
1	Valid

Subindex 0x02

Indicates whether the Value parameter contains a value in overrange.

Overrange Exceeded	
0	No Overrange Exceeded
1	Overrange Exceeded

Subindex 0x03

Indicates whether the Value parameter contains a value in underrange.

Underrange Exceeded	
0	No Underrange Exceeded
1	Underrange Exceeded

Subindex 0x05

Emission Status Off/On	
0	OFF
1	ON

Subindex 0x06

Degas Status Off/On	
0	OFF
1	ON

4.3.3 Input Trip Point 1

Index	SI	DataType	NV	Access	PM	Name
600E	0x01	BOOL		RO	tx	Status High Trip
	0x02	BOOL		RO	tx	Status Low Trip

Subindex 0x01

Status High Trip	
0	High Trip not assert
1	High Trip assert

Subindex 0x02

Status Low Trip	
0	Low Trip not assert
1	Low Trip assert

4.3.4 Input Trip Point 2

Index	SI	DataType	NV	Access	PM	Name
600F	0x01	BOOL		RO	tx	Status High Trip
	0x02	BOOL		RO	tx	Status Low Trip

Subindex 0x01

Status High Trip	
0	High Trip not assert
1	High Trip assert

Subindex 0x02

Status Low Trip	
0	Low Trip not assert
1	Low Trip assert

4.4 Configuration Area (0x8000…0x8FFF)

4.4.1 Configuration Hot Cathode Ion

Index	SI	DataType	NV	Access	PM	Name
8005	0x01	BOOL	x	RW		Filament User Mode
	0x02	BOOL	x	RW		Emission User Mode
	0x11	USINT	x	RW		Active Filament
	0x13	REAL	x	RW		Emission Current

Subindex 0x01

Defines whether the filament is switched automatically (automatic) or manually by the user (manual).
Defines whether the filament selection is static as defined by "Active Filament" (manual) or the active filament is changed always when the filament is switched on (automatic).

Filament User Mode	
0	Automatic
1	Manual

Subindex 0x02

Defines whether the emission is switched on automatically (controlled by a different sensor) (automatic) or manually by the user (manual).

Emission User Mode	
0	Automatic (not supported)
1	Manual

Subindex 0x11

Active Sensor filament.

Active Filament	
Bit 0	Filament 1 is on if Bit is set
Bit 1	Filament 2 is on if Bit is set
Bit 2…7	Always 0 (reserved)

Subindex 0x13

Emission current in milliamps

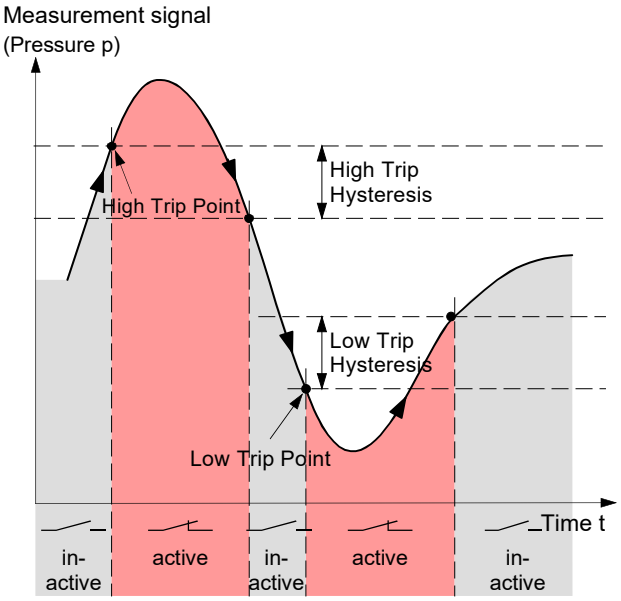
4.4.2 Configuration Trip Point 1

If High Trip Source Index is 0x800E1100 or 0x800F1100 the High Trip Point is equal with the value referenced in High Trip Point Limit.

The value defined in High Trip Point Limit is compared with the pressure value referenced by the Source Index parameter.

If Low Trip Source Index is 0x800E1400 or 0x800F1400 the Low Trip Point is equal with the value referenced in Low Trip Point Limit.

The value defined in Low Trip Point Limit is compared with the pressure value referenced by the Source Index parameter.



Index	SI	DataType	NV	Access	PM	Name
800E	0x01	BOOL	x	RW		High Trip Enable
	0x02	BOOL	x	RW		Low Trip Enable
	0x11	REAL	x	RW		High Trip Point Limit
	0x12	UDINT	x	RW		High Trip Source Index
	0x13	REAL	x	RW		Percentage High Trip Source
	0x14	REAL	x	RW		Low Trip Point Limit
	0x15	UDINT	x	RW		Low Trip Source Index
	0x16	REAL	x	RW		Percentage Low Trip Source
	0x17	REAL	x	RW		High Trip Hysteresis
	0x18	REAL	x	RW		Low Trip Hysteresis
	0x1A	UDINT	x	RW		Source Index

Subindex 0x01

High Trip Point Enable	
0	Disable
1	Enable

Subindex 0x02

Low Trip Point Enable	
0	Disable
1	Enable

Subindex 0x11

High Trip Point Limit: High limit to trigger trip point condition if Input Value (I 0x900E, SI 0x01) is above this limit.

Subindex 0x12

Object index of High Trip Point Value source.

Bit 16…31: Index
Bit 08…15: Subindex
Bit 00…07: reserved

It is only possible to reference to "High Trip Point Limit" (I”0x800E”, SI”0x11”).

Subindex 0x13

Percentage of Value referenced by High Trip Source Index in [%]. If High Trip Source Index is I”0x800E”, SI”0x11” this parameter is not used.

Subindex 0x14

Low Trip Point Limit: Low limit to trigger trip point condition if Input Value (I 0x900E", SI"0x01") is below this limit.

Subindex 0x15

Object index of Low Trip Point Value source. Index of Low Trip Point Limit.

Bit 16…31: Index
Bit 08…15: Subindex
Bit 00…07: reserved

It is only possible to reference to "Low Trip Point Limit" (I"0x800E", SI"0x14").

Subindex 0x16

Percentage of Value referenced by Low Trip Source Index in [%]. If Low Trip Source Index is I"0x800E", SI"0x14" this parameter is not used.

Subindex 0x17

High Trip Hysteresis: Hysteresis value for High Trip Point.

Subindex 0x18

Low Trip Hysteresis: Hysteresis value for Low Trip Point.

Subindex 0x1A

Object index of active source of (I"0x6000" SI"0x11") Input Value.

Source Index	
Bit 16…31	Index
Bit 08…15	Subindex
Bit 00…07	Reserved

4.4.3 Configuration Trip Point 2

Index	SI	DataType	NV	Access	PM	Name
800F	0x01	BOOL	x	RW		High Trip Enable
	0x02	BOOL	x	RW		Low Trip Enable
	0x11	REAL	x	RW		High Trip Point Limit
	0x12	UDINT	x	RW		High Trip Source Index
	0x13	REAL	x	RW		Percentage High Trip Source
	0x14	REAL	x	RW		Low Trip Point Limit
	0x15	UDINT	x	RW		Low Trip Source Index
	0x16	REAL	x	RW		Percentage Low Trip Source
	0x17	REAL	x	RW		High Trip Hysteresis
	0x18	REAL	x	RW		Low Trip Hysteresis
	0x1A	UDINT	x	RW		Source Index

Subindex 0x01

High Trip Point Enable	
0	Disable
1	Enable

Subindex 0x02

Low Trip Point Enable	
0	Disable
1	Enable

Subindex 0x11

High Trip Point limit: High limit to trigger trip point condition if Input Value (I 0x900F", SI 0x01") is above this limit.

Subindex 0x12

Object index of High Trip Point Value source.

Bit 16…31: Index
Bit 08…15: Subindex
Bit 00…07: reserved

It is only possible to reference to "High Trip Point Limit" (I”0x800F”, SI”0x11”).

Subindex 0x13

Percentage of Value referenced by High Trip Source Index in [%]. If High Trip Source Index is I”0x800F”, SI”0x11” this parameter is not used.

Subindex 0x14

Low Trip Point Limit: Low limit to trigger trip point condition if Input Value (I 0x900F”, SI 0x01”) is below this limit.

Subindex 0x15

Object index of Low Trip Point Value source. Index of Low Trip Point Limit (I 0x800F”, SI 0x14”).

Bit 16…31: Index
Bit 08…15: Subindex
Bit 00…07: reserved

It is only possible to reference to "Low Trip Point Limit" (I”0x800F” SI”0x14”).

Subindex 0x16

Percentage of Value referenced by Low Trip Source Index in [%].If Low Trip Source Index is I”0x800F”, SI”0x14” this parameter is not used.

Subindex 0x17

High Trip Hysteresis: Hysteresis value for High Trip Point.

Subindex 0x18

Low Trip Hysteresis: Hysteresis value for Low Trip Point.

Subindex 0x1A

Object index of active source of (I 0x6000 SI 0x11) Input Value.

Source Index	
Bit 16…31	Index
Bit 08…15	Subindex
Bit 00…07	Reserved

4.5 Information Area (0x9000…0x9FFF)

The Information Data object defines the input process data.

4.5.1 Information Hot Cathode Ion

Index	SI	DataType	NV	Access	PM	Name
9005	0x01	UINT		RO		Sensor Warning
	0x02	UINT		RO		Sensor Error

Subindex 0x01

Sensor Warnings	
Bit 0…15	0

Subindex 0x02

Sensor Errors	
Bit 0	Sensor Filament 1 Error
Bit 1	Sensor Filament 2 Error
Bit 2…8	0
Bit 9	Electronics Failure
Bit 10	Over Temperature of Electronics
Bit 11…15	0

4.5.2 Information Trip Point 1/2

Index	SI	DataType	NV	Access	PM	Name
900E	0x01	REAL		RO		Input value Trip Point 1
900F	0x01	REAL		RO		Input value Trip Point 1

Subindex 0x1(900E)

Input Value Trip Point 1: Trip Point Input value as referenced by Source Index (I 0x800E, SI 0x1A).

Subindex 0x1(900F)

Input Value Trip Point 1: Trip Point Input value as referenced by Source Index (I 0x800F, SI 0x1A).

4.6 Device Area (0xF000...0xAFFF)

4.6.1 Semiconductor Device Profile

Index	SI	DataType	NV	Access	PM	Name
F000	0x01	UINT		RO		Index Distance
	0x02	UINT		RO		Maximum Number of Modules

Subindex 0x01

Index Distance: Index offset between PDO entries of two consecutive modules (for ETG.5003 = 0x10), e.g. 0x6000, 0x6010.

Subindex 0x02

Maximum Number of Modules: For the BAG552 this value always is 1.

4.6.2 Module Profile List

Index	SI	DataType	NV	Access	PM	Name
F010	0x01	UDINT		RO		Module Profile List

Subindex 0x01

Each sub-index lists the profile-number of the corresponding module.

Subindex 0x02

Each sub-index lists the profile-number of the corresponding module.

4.6.3 Exceptions

4.6.4 Active Exception Status

Index	SI	DataType	NV	Access	PM	Name
F380		USINT		RO	tx	ActiveException Status

Active Exception Status

Active Exception Status	
Bit 0	Device Warning
Bit 1	Manufacturer Warning
Bit 2	Device Error
Bit 3	Manufacturer Error
Bit 4…7	0

4.6.5 Active Device Warning Details

The "active device warning details" parameter describes the warning state of the complete device.

Index	SI	DataType	NV	Access	PM	Name
F381	0x01	UDINT		RO	tx	Active Device Warning Details
F382	0x01	UDINT		RO	tx	Active Manufacturer Warning Details

Subindex 0x01

Active Device Warning Details (Index F381)	
Bit 0…31	0

Subindex 0x01

Active Manufacturer Warning Details (Index F382)	
Bit 0…31	0

4.6.6 Active Device Error Details

The "active device error details" parameter describes the error state of the complete device.

Index	SI	DataType	NV	Access	PM	Name
F383	0x01	UDINT		RO	tx	Active Device Error Details
F384	0x01	UDINT		RO	tx	Active Manufacturer Error Details

Subindex 0x01

Active Device Error Details (Index F383; Hot Cathode)	
Bit 0	Sensor Filament 1 Error
Bit 1	Sensor Filament 2 Error
Bit 2…8	0
Bit 9	Electronics Failure
Bit 10	Over Temperature of Electronics
Bit 11…15	0

Subindex 0x01

Active Manufacturer Error Details (Index F384)	
Bit 0…31	0

4.6.7 Active Global Device Warning Details

The "active global device warning details" parameter describes the warning state of the complete device.

Index	SI	DataType	NV	Access	PM	Name
F385	0x01	UDINT		RO	tx	Active Global Device Warning Details
F386	0x01	UDINT		RO	tx	Active Global Manufacturer Warning Details

Subindex 0x01

Active Global Device Warning Details (Index F385)	
Bit 0	0
Bit 1	uP exception
Bit 2	0
Bit 3	EEPROM exception
Bit 4…31	0

Subindex 0x01

Active Global Manufacturer Warning Details (Index F386)	
Bit 0…31	0

4.6.8 Active Global Device Error Details

The "active global device error details" parameter describes the error state of the complete device.

Index	SI	DataType	NV	Access	PM	Name
F387	0x01	UDINT		RO	tx	Active Global Device Error Details
F388	0x01	UDINT		RO	tx	Active Global Manufacturer Error Details

Subindex 0x01

Active Global Device Error Details (Index F387)	
Bit 0	0
Bit 1	uP exception
Bit 2	0
Bit 3	EEProm exception
Bit 4…31	0

Subindex 0x01

Active Global Manufacturer Error Details (Index F388)	
Bit 0…31	0

4.6.9 Latched Device Warning Details

Index	SI	DataType	NV	Access	PM	Name
F390		USINT		RO	tx	Latched Exceptions Status
F391	0x01	UDINT		RO	tx	Latched Device Warning Details
F392	0x01	UDINT		RO	tx	Latched Manufacturer Warning Details

Latched Exceptions Status

Latched version of 0xF380.

Subindex 0x01 (F391)

Latched Device Warning Details: Latched version of 0xF381:01.

Subindex 0x01 (F392)

Latched Manufacturer Warning Details: Latched version of 0xF382:01.

4.6.10 Latched Device Error Details

Index	SI	DataType	NV	Access	PM	Name
F393	0x01	UDINT		RO	tx	Latched Device Error Details
F394	0x01	UDINT		RO	tx	Latched Manufacturer Error Details

Subindex 0x01 (F393)

Latched Device Error Details: Latched version of 0xF383:01.

Subindex 0x01 (F394)

Latched Manufacturer Error Details: Latched version of 0xF384:01.

4.6.11 Latched Global Device Warning Details

Index	SI	DataType	NV	Access	PM	Name
F395	0x01	UDINT		RO	tx	Latched Global Device Warning Details
F396	0x01	UDINT		RO	tx	Latched Global Manufacturer Warning Details

Subindex 0x01 (F395) Latched Global Device Warning Details: Latched version of 0xF385:01.

Subindex 0x01 (F396) Latched Global Manufacturer Warning Details: Latched version of 0xF386:01.

4.6.12 Latched Global Device Error Details

Index	SI	DataType	NV	Access	PM	Name
F397	0x01	UDINT		RO	tx	Latched Global Device Error Details
F398	0x01	UDINT		RO	tx	Latched Global Manufacturer Error Details

Subindex 0x01 (F397) Latched Global Device Error Details: Latched version of 0xF387:01.

Subindex 0x01 (F398) Latched Global Manufacturer Error Details: Latched version of 0xF388:01.

4.6.13 Device Warning Mask

Index	SI	DataType	NV	Access	PM	Name
F3A1	0x01	UDINT	x	RW		Device Warning Mask
F3A2	0x01	UDINT	x	RW		Manufacturer Warning Mask

Subindex 0x01 (F3A1) Device Warning Mask: Mask bits for 0xF381:01 and 0xF391:01.

Subindex 0x01 (F3A2) Manufacturer Warning Mask: Mask bits for 0xF382:01 and 0xF392:01.

4.6.14 Device Error Mask

Index	SI	DataType	NV	Access	PM	Name
F3A3	0x01	UDINT	x	RW		Device Error Mask
F3A4	0x01	UDINT	x	RW		Manufacturer Error Mask

Subindex 0x01 (F3A3) Device Error Mask: Mask bits for 0xF383:01 and 0xF393:01.

Subindex 0x01 (F3A4) Manufacturer Error Mask: Mask bits for 0xF384:01 and 0xF394:01.

4.6.15 Global Device Warning Mask

Index	SI	DataType	NV	Access	PM	Name
F3A5	0x01	UDINT	x	RW		Global Device Warning Mask
F3A6	0x01	UDINT	x	RW		Global Manufacturer Warning Mask

Subindex 0x01 (F3A5) Global Device Warning Mask: Mask bits for 0xF385:01 and 0xF395:01.

Subindex 0x01 (F3A6) Global Manufacturer Warning Mask: Mask bits for 0xF386:01 and 0xF396:01.

4.6.16 Global Device Error Mask

Index	SI	DataType	NV	Access	PM	Name
F3A7	0x01	UDINT	x	RW		Global Device Error Mask
F3A8	0x01	UDINT	x	RW		Global Manufacturer Error Mask

Subindex 0x01 (F3A7)

Global Device Error Mask: Mask bits for 0xF387:01 and 0xF397:01.

Subindex 0x01 (F3A8)

Global Manufacturer Error Mask: Mask bits for 0xF388:01 and 0xF398:01.

4.6.17 Trip Point Output All

Index	SI	DataType	NV	Access	PM	Name
F641	0x01	UDINT		RO	tx	Trip Point Output All Instance

Subindex 0x01

Status of Trip Point instances.

Trip Point Output All Instance	
Bit 0	Status High Trip (I 0x600E, SI 0x01)
Bit 1	Status Low Trip (I 0x600E S,I 0x02)
Bit 2	Status High Trip (I 0x600F, SI 0x01)
Bit 3	Status Low Trip (I 0x600F, SI 0x02)
Bit 4…31	0

4.6.18 Input Latch Local Timestamp

Index	SI	DataType	NV	Access	PM	Name
F6F0	0x01	UDINT		RO	tx	Input Latch Local Timestamp

Subindex 0x01

Local controller time corresponding to the input latch time in microseconds. It starts at zero on device power-up. Mandatory if device has inputs. If device has no inputs defined, this corresponds the time immediately prior to writing to input SM.

4.6.19 Configure Device

Index	SI	DataType	NV	Access	PM		Name
F840	0x01	UDINT	x	RW			Data Units
	0x03	Enum	x	RW			Data Units Enum

Subindex 0x01

Unit of the Value of the Analog Input Sensor Instance and all related parameters.

Trip Point Output All Instance	
0x00220000	Pascal
0xFD4E0000	mbar
0x00A10000	Torr

If this value is changed, also Subindex 3 will change the value accordingly.

Subindex 0x03

Data Unit for Input Sensor as Enum to have a list of possible values.

Data Units	
0x01(Pa)	Pascal
0x04(mBar)	mbar
0x05(Torr)	Torr

If this value is changed, also Subindex 1 will change the value accordingly.

4.6.20 Information Device

Index	SI	DataType	NV	Access	PM	Name
F940	0x01	UDINT		RO		Measurement Principle
	0x02	BYTE		RO		Number of Sensors
F9F0		V_STRING		RO		Manufacturer Serial Number
F9F1	0x01	UDINT		RO		CDP Functional Generation Number
F9F2	0x01	UDINT		RO		SDP Functional Generation Number (Module 1)
F9F3		V_STRING		RO		Vendor Name
F9F4	0x01	V_STRING		RO		Semiconductor SDP Device Name (Module 1)
F9F5	0x01	USINT		RW	rx tx	Output Identifier
F9F6		UDINT		RO		Time since power on
F9F7		UDINT	x	RO		Total time powered
F9F8		UDINT		RO		Firmware Update Functional Generation Number

Subindex 0x01 (F940)

Measurement principle assigned to the object instance.

The most significant nibble of the parameter represents the sensor type of the first Module, the second most significant nibble of the parameter represents the sensor type of the second Module, and so forth.

Measurement Principle (Index F940)	
1	Capacitance Manometer
2	Piezo
3	Heat Transfer
4	Cold Cathode
5	Hot Cathode

Subindex 0x02 (F940)

Number of Sensors (Index F940): In this device is 1 sensor implemented.

4.6.21 Command Degas ON / OFF

Execution of this command will initiate or cancel a degas operation.

Index	SI	DataType	NV	Access	PM	Name
FB43	0x01	O_STRING(2)		RW		Command
	0x02	BYTE		RO		Status
	0x03	O_STRING(3)		RO		Response

Subindex 0x01

A degas command is initiated when the following byte sequence is sent.

Command	
Byte 0	0: Degas OFF 1: Degas ON
Byte 1	Index of the sensor module. Value has to be 1 1: Hot Cathode

Subindex 0x02

Status (supported values)	
0	Last command completed, no errors, no reply available
1	Last command completed, no errors, reply available
2	Last command completed, errors present, no reply available
3	Last command completed, errors present, reply available
255	Command is executing

Subindex 0x03

Response	
Byte 0	See Subindex 0x02
Byte 1	not used = 0x00
Byte 2	0: Degas ON / OFF successful 1: Degas ON / OFF failed (unspecified reason) 2: Degas On failed because pressure to high 254: No previous Degas ON / OFF command issued

4.6.22 Command Emission ON / OFF

Execution of this command will turn on or off the gauge's emission state.

Index	SI	DataType	NV	Access	PM	Name
FB44	0x01	O_STRING(2)		RW		Command
	0x02	BYTE		RO		Status
	0x03	O_STRING(3)		RO		Response

Subindex 0x01

An emission command is initiated when the following byte sequence is sent.

Command	
Byte 0	0: Emission OFF 1: Emission ON
Byte 1	Index of the sensor module. Value has to be 1 1: Hot Cathode

Subindex 0x02

Status (supported values)	
0	Last command completed, no errors, no reply available
1	Last command completed, no errors, reply available
2	Last command completed, errors present, no reply available
3	Last command completed, errors present, reply available
255	Command is executing

Subindex 0x03

Response	
Byte 0	See Subindex 0x02
Byte 1	not used = 0x00
Byte 2	0: Emission ON / OFF successful 1: Emission ON / OFF failed (unspecified reason) 2: Emission On failed because pressure to high 254: No previous Emission ON / OFF command issued

4.6.23 Device Reset Command

Execution of this command causes the device to emulate a complete power cycle. This includes an ESC reset. An SDP may limit some behavior of the power cycle emulation, but shall not exclude the EtherCAT interface.

As consequence of an ESC reset all following devices are disconnected from the network.

There are two versions of this command:

- Standard reset (as described above)
- Factory reset (as described above, but additionally, all parameters are restored to as-shipped defaults).

Index	SI	DataType	NV	Access	PM	Name
FBF0	0x01	O_STRING(6)		RW		Command
	0x02	BYTE		RO		Status
	0x03	O_STRING(2)		RO		Response

Subindex 0x01

A device reset is initiated when the following byte sequence is sent.

Command	
Byte 0	0x74
Byte 1	0x65
Byte 2	0x73
Byte 3	0x65
Byte 4	0x72
Byte 5	0x00 = Standard reset, 0x66 = Factory Reset

Subindex 0x02

Status (supported values)	
0	Reserved
1	Reserved
2	Last command completed, error, no response
3	Reserved
255	Command is executing

Subindex 0x03

Response	
Byte 0	See Subindex 0x02
Byte 1	not used = 0x00

4.6.24 Exception Reset Command

Execution of this command clears the latched exceptions.

Index	SI	DataType	NV	Access	PM	Name
FBF1	0x01	O_STRING(5)		RW		Command
	0x02	BYTE		RO		Status
	0x03	O_STRING(2)		RO		Response

Subindex 0x01

An exception reset is initiated when the following byte sequence is sent.

Command	
Byte 0	0x74
Byte 1	0x65
Byte 2	0x73
Byte 3	0x65
Byte 4	0x72

Subindex 0x02

Status (supported values)	
0	Last command completed, no error, no response
1	Reserved
2	Last command completed, error, no response
3	Reserved
255	Command is executing

Subindex 0x03

Response	
Byte 0	See Subindex 0x02
Byte 1	not used = 0x00

4.6.25 Store Parameters Command

Execution of this command will store all parameters to non-volatile memory. If a device automatically saves all non-volatile parameters at the time they are set, this command will not take any action.

Index	SI	DataType	NV	Access	PM	Name
FBF2	0x01	O_STRING(4)		RW		Command
	0x02	BYTE		RO		Status
	0x03	O_STRING(2)		RO		Response

Subindex 0x01

A device reset is initiated when the following byte sequence is sent.

Read:

Command: Read	
Byte 0	0x01 = slave saves the non-volatile parameters when writing 0xFBF2:01 with 0x65766173
Byte 1	not used = 0x00
Byte 2	not used = 0x00
Byte 3	not used = 0x00

Write:

Command: Write	
Byte 0	0x73
Byte 1	0x61
Byte 2	0x76
Byte 3	0x65

Subindex 0x02

Status (supported values)	
0	Last command completed, no error, no response
1	Reserved
2	Last command completed, error, no response
3	Reserved
255	Command is executing

Subindex 0x03

Response	
Byte 0	See Subindex 0x02
Byte 1	not used = 0x00

4.6.26 Calculate Checksum Command

Execution of this command will calculate a checksum for all writable, non-volatile parameters as currently stored in non-volatile memory.

Index	SI	DataType	NV	Access	PM	Name
FBF3	0x01	O_STRING(4)		RW		Command
	0x02	BYTE		RO		Status
	0x03	O_STRING(6)		RO		Response

Subindex 0x01

A device reset is initiated when the following byte sequence is sent.

Read

Command: Read	
Byte 0	Bit 0 = 1: non-volatile parameters supported Bit 1 = 1: CRC-32 Bit 2..7 = 0: not used
Byte 1	not used = 0x00
Byte 2	not used = 0x00
Byte 3	not used = 0x00

Write

Command: Write	
Byte 0	Bit 0 = 1: use default checksum algorithm of the slave Bit 1 = 1: CRC-32 Bit 2..7 = 0: not used
Byte 1	not used = 0x00
Byte 2	not used = 0x00
Byte 3	not used = 0x00

Subindex 0x02

Status (supported values)	
0	Last command completed, no error, no response
1	Reserved
2	Last command completed, error, no response
3	Reserved
255	Command is executing

Subindex 0x03

Response	
Byte 0	See Subindex 0x02
Byte 1	not used = 0
Byte 2	Checksum return value, Byte 0
Byte 3	Checksum return value, Byte 1
Byte 4	Checksum return value, Byte 2
Byte 5	Checksum return value, Byte 3

4.6.27 Load Parameters Command

Execution of this command will load all parameters from non-volatile memory.

Index	SI	DataType	NV	Access	PM	Name
FBF4	0x01	O_STRING(4)		RW		Command
	0x02	BYTE		RO		Status
	0x03	O_STRING(2)		RO		Response

Subindex 0x01

A device reset is initiated when the following byte sequence is sent.

Read:

Command: Read	
Byte 0	0x01 = slave loads the non-volatile parameters when writing 0xFBF4:01 with 0x64616F6C
Byte 1	not used = 0x00
Byte 2	not used = 0x00
Byte 3	not used = 0x00

Write:

Command: Write	
Byte 0	0x6C
Byte 1	0x6F
Byte 2	0x61
Byte 3	0x64

Subindex 0x02

Status (supported values)	
0	Last command completed, no error, no response
1	Reserved
2	Last command completed, error, no response
3	Reserved
255	Command is executing

Subindex 0x03

Response	
Byte 0	See Subindex 0x02
Byte 1	not used = 0x00

5 BPG552: Object Structure

This chapter describes the CANopen over EtherCAT (CoE) Object Dictionary.

5.1 Object Dictionary structure

The objects in the CoE Object Dictionary can be accessed with SDO services, and many of the dictionary objects can be mapped for cyclic communication in PDO's. Each object is addressed using a 16-bit index and an 8-bit subindex.

The following table presents the overall layout of the standard Object Dictionary.

Index (hex.)	Object dictionary area	
1000 – 1FFF	Communication profile area	
2000 – 5FFF	Manufacturer-specific profile area	
6000 – 6FFF	Profile Specific Area	Input area
7000 – 7FFF		Output area
8000 – 8FFF		Configuration area
9000 – 9FFF		Information area
A000 – AFFF		Diagnosis area
B000 – BFFF		Service Transfer area
C000 – EFFF		Reserved area
F000 – FFFF		Device area

Explanations for the abbreviations in the columns of the tables are given below:

Abbr.	Description
Access	SDO read/write access • RO: object can only be read by the SDO service • RW: object can be both read and written by the SDO service
CoE	CAN application protocol over EtherCAT
Index	Object Index (hex.) (address of an object)
NV	Nonvolatile; attribute value is maintained through power cycles
Object	Abstract representation of a particular component within a device, which consists of data, parameters, and methods.
PDO	Process Data Object. Structure described by mapping parameters containing one or several process data entities.
PM	PDO mapping • Rx: object can be mapped into an Rx PDO • Tx : object can be mapped into a Tx PDO
RxPDO	Receive PDO. A Process Data Object received by an EtherCAT slave.
SDO	Service Data Objects. CoE asynchronous mailbox communications where all objects in the Object Dictionary can be read and written.
SI	Subindex (hex.) (sub-address of an object)
Type	Data Type • BOOL, BIT = 1 bit. Boolean (0 = false, 1 = true) • USINT, BYTE = 8 bit. Unsigned Byte • UINT = 16 bit. Unsigned integer value • UDINT = 32 bit. Unsigned integer value • ULINT = 64 bit. Unsigned integer value • REAL = 32 bit. Floating point • V_STRING = 8×n bit. Visible string (1 byte for character) • O_STRING = 8xn bit. Octet string (1 byte for element)
TxPDO	Transmit PDO. A Process Data Object sent from an EtherCAT slave.

5.2 Communication Profile Objects (0x1000…0x1FFF)

The objects of the communication profile describe the basic EtherCAT properties of the BPG552 and are common to all EtherCAT slaves using the CoE communication protocol. The objects are described in following table:

Index	SI	DataType	NV	Access	PM	Name
1000		UDINT		RO		Device Type 0x0000138B => 0x138B = dec 5003
1008		V_STRING		RO		Manufacturer Device name
1009		V_STRING		RO		Manufacturer Hardware Version
100A		V_STRING		RO		Manufacturer Software Version
100B		V_STRING		RO		Manufacturer Bootloader Version
1018				RO		Identity Object
	0x01	UDINT		RO		Vendor ID
	0x02	UDINT		RO		Product Code
	0x03	UDINT		RO		Revision Number
	0x04	UDINT		RO		Serial Number
10F8		ULINT		RO		Timestamp Object

5.2.1 Process Data Objects (PDO's)

The BPG552 consists of two vacuum pressure sensors. The characteristic of this combo device is that only one vacuum pressure sensor outputs an actual pressure value at one time. The other sensor is in overrange condition which means that the pressure is higher than the measurement range of the sensor or underrange condition which means that the pressure is lower than the measurement of the sensor. The 'Combination Gauge Active Value' outputs the pressure value form the active measuring sensor.
For each sensor module a default mapping is configured. The mapping for each sensor module has the same contents. For a compact cyclic data frame duplicated mappings can be deactivated.

Or to meet other requirements the TxPDO's 1A01 or 1A03 and the RxPDO 1601 are designated for user mapping. These PDO's do not have default values and can be set up by the PDO configuration.

RxPDO's

Index	SI	DataType	NV	Access	PM	Name
1600		PM		RW		RxPDO Receive PDO Mapping,
1601		PM		RW		RxPDO Receive PDO Mapping, User Mapping

TxPDO's

Index	SI	DataType	NV	Access	PM	Name
1A00		PM		RW		TxPDO Transmit PDO Mapping
1A01		PM		RW		TxPDO Transmit PDO Mapping, User Mapping
1A02		PM		RW		TxPDO Transmit PDO Mapping
1A03		PM		RW		TxPDO Transmit PDO Mapping, User Mapping
1BFE		PM		RW		Transmit PDO Mapping
	0x01	UDINT				0xF3800008 for Active Exception Status
	0x02	UDINT				0xF6400101 for Combination Gauge Reading Valid
	0x03	UDINT				0xF6400201 for Combination Gauge Overrange Exceeded
	0x04	UDINT				0xF6400301 for Combination Gauge Underrange Exceeded
	0x05	UDINT				0x00000005 for Padding Bits 1 (5 Bit)
	0x06	UDINT				0xF6401216 for Combination Gauge Active Value
	0x07	UDINT				0xF6401132 for Combination Gauge Active Sensor Number
	0x08	UDINT				0xF6410132 for Trip Point Output All Instance
1BFF		PM		RW		TxPDO Transmit PDO Mapping Device, User Mapping
1C00	0x01 0x02 0x03 0x04	BYTE		RW		Sync Manager Type
1C12 / 1C13	0x01 0x02 0x03 0x04	UINT		RW		Sync Manager PDO Assignment
1C32 / 1C33	0x01 - 0x20			RW		Sync Manager Parameter

5.3 Input Area (0x6000…0x6FFF)

5.3.1 Input Common Heat Transfer

Index	SI	DataType	NV	Access	PM	Name
6000	0x0E	BOOL		RO	tx	TxPdoState
	0x11	REAL		RO	tx	Sensor Value

Subindex 0x0E

Is set if the device is not in Safe State (value (I 0x6000, SI 0x11) = valid).

TxPdoState	
0	Invalid
1	Valid

Subindex 0x11

The corrected, converted, calibrated final analog input value of the sensor.

5.3.2 Input Heat Transfer

Index	SI	DataType	NV	Access	PM	Name
6003	0x01	BOOL		RO	tx	Reading Valid
	0x02	BOOL		RO	tx	Overrange Exceeded
	0x03	BOOL		RO	tx	Underrange Exceeded

Subindex 0x01

Indicates whether the Value parameter contains a valid value within the specified accuracy or not.

Reading Valid	
0	Invalid
1	Valid

Subindex 0x02

Indicates whether the Value parameter contains a value in overrange.

Overrange Exceeded	
0	No Overrange Exceeded
1	Overrange Exceeded

Subindex 0x03

Indicates whether the Value parameter contains a value in underrange.

Underrange Exceeded	
0	No Underrange Exceeded
1	Underrange Exceeded

5.3.3 Input Common Hot Cathode Ion

Index	SI	DataType	NV	Access	PM	Name
6010	0x0E	BOOL		RO	tx	TxPdoState
	0x11	REAL		RO	tx	Sensor Value

Subindex 0x0E

Is set if the device is not in Safe State (value (I 0x6010, SI 0x11) = valid).

TxPdoState	
0	Invalid
1	Valid

Subindex 0x11

The corrected, converted, calibrated final analog input value of the sensor.

5.3.4 Input Hot Cathode Ion

Index	SI	DataType	NV	Access	PM	Name
6015	0x01	BOOL		RO	tx	Reading Valid
	0x02	BOOL		RO	tx	Overrange Exceeded
	0x03	BOOL		RO	tx	Underrange Exceeded
	0x05	BOOL		RO	tx	Emission Status Off/On
	0x06	BOOL		RO	tx	Degas Status Off/On

Subindex 0x01

Indicates whether the Value parameter contains a valid value within the specified accuracy or not.

Reading Valid	
0	Invalid
1	Valid

Subindex 0x02

Indicates whether the Value parameter contains a value in overrange.

Overrange Exceeded	
0	No Overrange Exceeded
1	Overrange Exceeded

Subindex 0x03

Indicates whether the Value parameter contains a value in underrange.

Underrange Exceeded	
0	No Underrange Exceeded
1	Underrange Exceeded

Subindex 0x05

Emission Status Off/On	
0	OFF
1	ON

Subindex 0x06

Degas Status Off/On	
0	OFF
1	ON

5.3.5 Input Trip Point 1

Index	SI	DataType	NV	Access	PM	Name
600E	0x01	BOOL		RO	tx	Status High Trip
	0x02	BOOL		RO	tx	Status Low Trip

Subindex 0x01

Status High Trip	
0	High Trip not assert
1	High Trip assert

Subindex 0x02

Status Low Trip	
0	Low Trip not assert
1	Low Trip assert

5.3.6 Input Trip Point 2

Index	SI	DataType	NV	Access	PM	Name
600F	0x01	BOOL		RO	tx	Status High Trip
	0x02	BOOL		RO	tx	Status Low Trip

Subindex 0x01

Status High Trip	
0	High Trip not assert
1	High Trip assert

Subindex 0x02

Status Low Trip	
0	Low Trip not assert
1	Low Trip assert

5.4 Configuration Area (0x8000…0x8FFF)

5.4.1 Configuration Hot Cathode Ion

Index	SI	DataType	NV	Access	PM	Name
8015	0x01	BOOL	x	RW		Filament User Mode
	0x02	BOOL	x	RW		Emission User Mode
	0x11	USINT	x	RW		Active Filament
	0x13	REAL	x	RW		Emission Current

Subindex 0x01

Defines whether the filament is switched automatically (automatic) or manually by the user (manual).
Defines whether the filament selection is static as defined by "Active Filament" (manual) or the active filament is changed always when the filament is switched on (automatic).

Filament User Mode	
0	Automatic
1	Manual

Subindex 0x02

Defines whether the emission is switched on automatically (controlled by a different sensor) (automatic) or manually by the user (manual).

Emission User Mode	
0	Automatic
1	Manual

Subindex 0x11

Active Sensor filament.

Active Filament	
Bit 0	Filament 1 is on if Bit is set
Bit 1	Filament 2 is on if Bit is set
Bit 2…7	Always 0 (reserved)

Subindex 0x13

Emission current in milliamps.

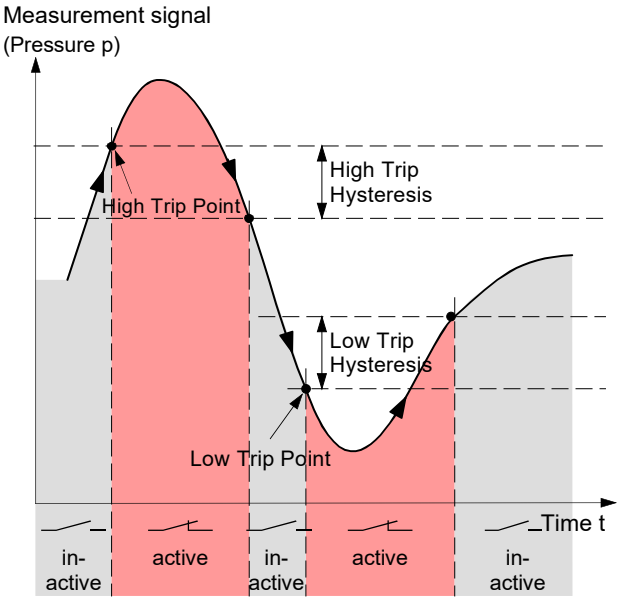
5.4.2 Configuration Trip Point 1

If High Trip Source Index is 0x800E1100 or 0x800F1100 the High Trip Point is equal with the value referenced in High Trip Point Limit.

The value defined in High Trip Point Limit is compared with the pressure value referenced by the Source Index parameter.

If Low Trip Source Index is 0x800E1400 or 0x800F1400 the Low Trip Point is equal with the value referenced in Low Trip Point Limit.

The value defined in Low Trip Point Limit is compared with the pressure value referenced by the Source Index parameter.



Index	SI	DataType	NV	Access	PM	Name
800E	0x01	BOOL	x	RW		High Trip Enable
	0x02	BOOL	x	RW		Low Trip Enable
	0x11	REAL	x	RW		High Trip Point Limit
	0x12	UDINT	x	RW		High Trip Source Index
	0x13	REAL	x	RW		Percentage High Trip Source
	0x14	REAL	x	RW		Low Trip Point Limit
	0x15	UDINT	x	RW		Low Trip Source Index
	0x16	REAL	x	RW		Percentage Low Trip Source
	0x17	REAL	x	RW		High Trip Hysteresis
	0x18	REAL	x	RW		Low Trip Hysteresis
	0x1A	UDINT	x	RW		Source Index

Subindex 0x01

High Trip Point Enable	
0	Disable
1	Enable

Subindex 0x02

Low Trip Point Enable	
0	Disable
1	Enable

Subindex 0x11

High Trip Point Limit: High limit to trigger trip point condition if Input Value (I”0x900E”, SI”0x01”) is above this limit.

Subindex 0x12

Object index of High Trip Point Value source

Bit 16…31: Index
Bit 08…15: Subindex
Bit 00…07: reserved

It is only possible to reference to "High Trip Point Limit" (I”0x800E”, SI”0x11”).

Subindex 0x13

Percentage of Value referenced by High Trip Source Index in [%]. If High Trip Source Index is I”0x800E”, SI”0x11” this parameter is not used.

Subindex 0x14

Low Trip Point Limit: Low limit to trigger trip point condition if Input Value (I 0x900E”, SI”0x01”) is below this limit.

Subindex 0x15

Object index of Low Trip Point Value source. Index of Low Trip Point Limit

Bit 16…31: Index
Bit 08…15: Subindex
Bit 00…07: reserved

It is only possible to reference to "Low Trip Point Limit" (I”0x800E”, SI”0x14”).

Subindex 0x16

Percentage of Value referenced by Low Trip Source Index in [%]. If Low Trip Source Index is I”0x800E”, SI”0x14” this parameter is not used.

Subindex 0x17

High Trip Hysteresis: Hysteresis value for High Trip Point.

Subindex 0x18

Low Trip Hysteresis: Hysteresis value for Low Trip Point.

Subindex 0x1A

Object index of active source of (I”0xF640” SI”0x11”) Input Value.

Source Index	
Bit 16…31	Index
Bit 08…15	Subindex
Bit 00…07	Reserved

5.4.3 Configuration Trip Point 2

Index	SI	DataType	NV	Access	PM	Name
800F	0x01	BOOL	x	RW		High Trip Enable
	0x02	BOOL	x	RW		Low Trip Enable
	0x11	REAL	x	RW		High Trip Point Limit
	0x12	UDINT	x	RW		High Trip Source Index
	0x13	REAL	x	RW		Percentage High Trip Source
	0x14	REAL	x	RW		Low Trip Point Limit
	0x15	UDINT	x	RW		Low Trip Source Index
	0x16	REAL	x	RW		Percentage Low Trip Source
	0x17	REAL	x	RW		High Trip Hysteresis
	0x18	REAL	x	RW		Low Trip Hysteresis
	0x1A	UDINT	x	RW		Source Index

Subindex 0x01

High Trip Point Enable	
0	Disable
1	Enable

Subindex 0x02

Low Trip Point Enable	
0	Disable
1	Enable

Subindex 0x11

High Trip Point Limit: High limit to trigger trip point condition if Input Value (I 0x900F, SI 0x01) is above this limit.

Subindex 0x12

Object index of High Trip Point Value source.

Bit 16…31: Index
Bit 08…15: Subindex
Bit 00…07: reserved

It is only possible to reference to "High Trip Point Limit" (I”0x800F”, SI”0x11”).

Subindex 0x13

Percentage of Value referenced by High Trip Source Index in [%]. If High Trip Source Index is I”0x800F”, SI”0x11” this parameter is not used.

Subindex 0x14

Low Trip Point Limit: Low limit to trigger trip point condition if Input Value (I 0x900F”, SI 0x01”) is below this limit.

Subindex 0x15

Object index of Low Trip Point Value source. Index of Low Trip Point Limit.

Bit 16…31: Index
Bit 08…15: Subindex
Bit 00…07: reserved

It is only possible to reference to "Low Trip Point Limit" (I”0x800F” SI”0x14”).

Subindex 0x16

Percentage of Value referenced by Low Trip Source Index in [%].If Low Trip Source Index is I”0x800F”, SI”0x14” this parameter is not used.

Subindex 0x17

High Trip Hysteresis: Hysteresis value for High Trip Point.

Subindex 0x18

Low Trip Hysteresis: Hysteresis value for Low Trip Point.

Subindex 0x1A

Object index of active source of (I 0xF640 SI 0x11) Input Value.

Source Index	
Bit 16…31	Index
Bit 08…15	Subindex
Bit 00…07	Reserved

5.5 Information Area (0x9000…0x9FFF)

The Information Data object defines the input process data.

5.5.1 Information Heat Transfer

Index	SI	DataType	NV	Access	PM	Name
9003	0x01	UINT		RO		Sensor Warning
	0x02	UINT		RO		Sensor Error

Subindex 0x01

Sensor Warnings	
Bit 0…15	0

Subindex 0x02

Sensor Errors	
Bit 0	0
Bit 1	Electronics Failure
Bit 2…15	0

5.5.2 Information Hot Cathode Ion

Index	SI	DataType	NV	Access	PM	Name
9015	0x01	UINT		RO		Sensor Warning
	0x02	UINT		RO		Sensor Error

Subindex 0x01

Sensor Warnings	
Bit 0…15	0

Subindex 0x02

Sensor Errors	
Bit 0	Sensor Filament 1 Error
Bit 1	Sensor Filament 2 Error
Bit 2…8	0
Bit 9	Electronics Failure
Bit 10	Over Temperature of Electronics
Bit 11…15	0

5.5.3 Information Trip Point 1/2

Index	SI	DataType	NV	Access	PM	Name
900E	0x01	REAL		RO		Input value Trip Point 1
900F	0x01	REAL		RO		Input value Trip Point 1

Subindex 0x1(900E)

Input Value Trip Point 1: Trip Point Input value as referenced by Source Index (I 0x800E, SI 0x1A).

Subindex 0x1(900F)

Input Value Trip Point 1: Trip Point Input value as referenced by Source Index (I 0x800F, SI 0x1A).

5.6 Device Area (0xF000...0xAFFF)

5.6.1 Semiconductor Device Profile

Index	SI	DataType	NV	Access	PM	Name
F000	0x01	UINT		RO		Index Distance
	0x02	UINT		RO		Maximum Number of Modules

Subindex 0x01

Index Distance: Index offset between PDO entries of two consecutive modules (for ETG.5003 = 0x10), e.g. 0x6000, 0x6010.

Subindex 0x02

Maximum Number of Modules: For the BPG552 this value always is 2.

5.6.2 Module Profile List

Index	SI	DataType	NV	Access	PM	Name
F010	0x01	UDINT		RO		Module Profile List
	0x02	UDINT		RO		Module Profile List

Subindex 0x01

Each sub-index lists the profile-number of the corresponding module.

Subindex 0x02

Each sub-index lists the profile-number of the corresponding module.

5.6.3 Exceptions

5.6.4 Active Exception Status

Index	SI	DataType	NV	Access	PM	Name
F380		USINT		RO	tx	Active Exception Status

Active Exception Status

Active Exception Status	
Bit 0	Device Warning
Bit 1	Manufacturer Warning
Bit 2	Device Error
Bit 3	Manufacturer Error
Bit 4…7	0

5.6.5 Active Device Warning Details

The "active device warning details" parameter describes the warning state of the complete device.

Index	SI	DataType	NV	Access	PM	Name
F381	0x01	UDINT		RO	tx	Active Device Warning Details
	0x02	UDINT		RO	tx	Active Device Warning Details
F382	0x01	UDINT		RO	tx	Active Manufacturer Warning Details
	0x02	UDINT		RO	tx	Active Manufacturer Warning Details

Subindex 0x01

Active Device Warning Details (Index F381)	
Bit 0…31	0

Subindex 0x02

Active Device Warning Details (Index F381)	
Bit 0…31	0

Subindex 0x01

Active Manufacturer Warning Details (Index F382)	
Bit 0…31	0

Subindex 0x02

Active Manufacturer Warning Details (Index F382)	
Bit 0…31	0

5.6.6 Active Device Error Details

The "active device error details" parameter describes the error state of the complete device.

Index	SI	DataType	NV	Access	PM	Name
F383	0x01	UDINT		RO	tx	Active Device Error Details
	0x02	UDINT		RO	tx	Active Device Error Details
F384	0x01	UDINT		RO	tx	Active Manufacturer Error Details
	0x02	UDINT		RO	tx	Active Manufacturer Error Details

Subindex 0x01

Active Device Error Details (Index F383; Piezo)	
Bit 0	0
Bit 1	Electronics failure
Bit 2…31	0

Subindex 0x02

Active Device Error Details (Index F383; Hot Cathode)	
Bit 0	Sensor Filament 1 Error
Bit 1	Sensor Filament 2 Error
Bit 2…8	0
Bit 9	Electronics Failure
Bit 10	Over Temperature of Electronics
Bit 11…15	0

Subindex 0x01

Active Manufacturer Error Details (Index F384)	
Bit 0…31	0

Subindex 0x02

Active Manufacturer Error Details (Index F384)	
Bit 0…31	0

5.6.7 Active Global Device Warning Details

The "active global device warning details" parameter describes the warning state of the complete device.

Index	SI	DataType	NV	Access	PM	Name
F385	0x01	UDINT		RO	tx	Active Global Device Warning Details
F386	0x01	UDINT		RO	tx	Active Global Manufacturer Warning Details

Subindex 0x01

Active Global Device Warning Details (Index F385)	
Bit 0	0
Bit 1	uP exception
Bit 2	0
Bit 3	EEPROM exception
Bit 4…31	0

Subindex 0x01

Active Global Manufacturer Warning Details (Index F386)	
Bit 0…31	0

5.6.8 Active Global Device Error Details

The "active global device error details" parameter describes the error state of the complete device.

Index	SI	DataType	NV	Access	PM	Name
F387	0x01	UDINT		RO	tx	Active Global Device Error Details
F388	0x01	UDINT		RO	tx	Active Global Manufacturer Error Details

Subindex 0x01

Active Global Device Error Details (Index F387)	
Bit 0	0
Bit 1	uP exception
Bit 2	0
Bit 3	EEProm exception
Bit 4…31	0

Subindex 0x01

Active Global Manufacturer Error Details (Index F388)	
Bit 0…31	0

5.6.9 Latched Device Warning Details

Index	SI	DataType	NV	Access	PM	Name
F390		USINT		RO	tx	Latched Exceptions Status
F391	0x01	UDINT		RO	tx	Latched Device Warning Details
	0x02	UDINT		RO	tx	Latched Device Warning Details
F392	0x01	UDINT		RO	tx	Latched Manufacturer Warning Details
	0x02	UDINT		RO	tx	Latched Manufacturer Warning Details

Latched Exceptions Status

Latched version of 0xF380.

Subindex 0x01 (F391)

Latched Device Warning Details: Latched version of 0xF381:01.

Subindex 0x02 (F391)

Latched Device Warning Details: Latched version of 0xF381:02.

Subindex 0x01 (F392)

Latched Manufacturer Warning Details: Latched version of 0xF382:01.

Subindex 0x02 (F392)

Latched Manufacturer Warning Details: Latched version of 0xF382:02.

5.6.10 Latched Device Error Details

Index	SI	DataType	NV	Access	PM	Name
F393	0x01	UDINT		RO	tx	Latched Device Error Details
	0x02	UDINT		RO	tx	Latched Device Error Details
F394	0x01	UDINT		RO	tx	Latched Manufacturer Error Details
	0x02	UDINT		RO	tx	Latched Manufacturer Error Details

Subindex 0x01 (F393)

Latched Device Error Details: Latched version of 0xF383:01.

Subindex 0x02 (F393)

Latched Device Error Details: Latched version of 0xF383:02.

Subindex 0x01 (F394)

Latched Manufacturer Error Details: Latched version of 0xF384:01.

Subindex 0x02 (F394)

Latched Manufacturer Error Details: Latched version of 0xF384:02.

5.6.11 Latched Global Device Warning Details

Index	SI	DataType	NV	Access	PM	Name
F395	0x01	UDINT		RO	tx	Latched Global Device Warning Details
F396	0x01	UDINT		RO	tx	Latched Global Manufacturer Warning Details

Subindex 0x01 (F395) Latched Global Device Warning Details: Latched version of 0xF385:01.

Subindex 0x01 (F396) Latched Global Manufacturer Warning Details: Latched version of 0xF386:01.

5.6.12 Latched Global Device Error Details

Index	SI	DataType	NV	Access	PM	Name
F397	0x01	UDINT		RO	tx	Latched Global Device Error Details
F398	0x01	UDINT		RO	tx	Latched Global Manufacturer Error Details

Subindex 0x01 (F397) Latched Global Device Error Details: Latched version of 0xF387:01.

Subindex 0x01 (F398) Latched Global Manufacturer Error Details: Latched version of 0xF388:01.

5.6.13 Device Warning Mask

Index	SI	DataType	NV	Access	PM	Name
F3A1	0x01	UDINT	x	RW		Device Warning Mask
	0x02	UDINT	x	RW		Device Warning Mask
F3A2	0x01	UDINT	x	RW		Manufacturer Warning Mask
	0x02	UDINT	x	RW		Manufacturer Warning Mask

Subindex 0x01 (F3A1) Device Warning Mask: Mask bits for 0xF381:01 and 0xF391:01.

Subindex 0x02 (F3A1) Device Warning Mask: Mask bits for 0xF381:02 and 0xF391:02.

Subindex 0x01 (F3A2) Manufacturer Warning Mask: Mask bits for 0xF382:01 and 0xF392:01.

Subindex 0x02 (F3A2) Manufacturer Warning Mask: Mask bits for 0xF382:02 and 0xF392:02.

5.6.14 Device Error Mask

Index	SI	DataType	NV	Access	PM	Name
F3A3	0x01	UDINT	x	RW		Device Error Mask
	0x02	UDINT	x	RW		Device Error Mask
F3A4	0x01	UDINT	x	RW		Manufacturer Error Mask
	0x02	UDINT	x	RW		Manufacturer Error Mask

Subindex 0x01 (F3A3) Device Error Mask: Mask bits for 0xF383:01 and 0xF393:01.

Subindex 0x02 (F3A3) Device Error Mask: Mask bits for 0xF383:02 and 0xF393:02.

Subindex 0x01 (F3A4) Manufacturer Error Mask: Mask bits for 0xF384:01 and 0xF394:01.

Subindex 0x02 (F3A4)

Manufacturer Error Mask: Mask bits for 0xF384:02 and 0xF394:02.

5.6.15 Global Device Warning Mask

Index	SI	DataType	NV	Access	PM	Name
F3A5	0x01	UDINT	x	RW		Global Device Warning Mask
F3A6	0x01	UDINT	x	RW		Global Manufacturer Warning Mask

Subindex 0x01 (F3A5)

Global Device Warning Mask: Mask bits for 0xF385:01 and 0xF395:01.

Subindex 0x01 (F3A6)

Global Manufacturer Warning Mask: Mask bits for 0xF386:01 and 0xF396:01.

5.6.16 Global Device Error Mask

Index	SI	DataType	NV	Access	PM	Name
F3A7	0x01	UDINT	x	RW		Global Device Error Mask
F3A8	0x01	UDINT	x	RW		Global Manufacturer Error Mask

Subindex 0x01 (F3A7)

Global Device Error Mask: Mask bits for 0xF387:01 and 0xF397:01.

Subindex 0x01 (F3A8)

Global Manufacturer Error Mask: Mask bits for 0xF388:01 and 0xF398:01.

5.6.17 Combination Gauge

Index	SI	DataType	NV	Access	PM	Name
F640	0x01	BOOL		RO	tx	Combination Gauge Reading Valid
	0x02	BOOL		RO	tx	Combination Gauge Overrange Exceeded
	0x03	BOOL		RO	tx	Combination Gauge Underrange Exceeded
	0x11	REAL		RO	tx	Combination Gauge Active Value
	0x12	UINT		RO	tx	Combination Gauge Active Sensor Number

Subindex 0x01

Identifies whether the complete vacuum pressure gauge (with several measuring principles) is out of its absolute overrange or absolute underrange, or in any other failure condition.

Subindex 0x02

If the bit "Overrange" is set, all modules of the gauge are in an overrange condition.

Subindex 0x03

If the bit "Underrange" is set, all modules of the gauge are in an underrange condition

Subindex 0x11

The value copied from the measurement value of the active measuring module used for the Input PDO.

Subindex 0x12

Identifies the module that is providing the measurement value, the latter of which is copied into the Active Value parameter for all Input PDO’s.

0	No module has a valid value
3	Heat Transfer sensor is providing the Active Value
4	Hot Cathode sensor is providing the Active Value

5.6.18 Trip Point Output All

Index	SI	DataType	NV	Access	PM	Name
F641	0x01	UDINT		RO	tx	Trip Point Output All Instance

Subindex 0x01

Status of Trip Point instances.

Trip Point Output All Instance	
Bit 0	Status High Trip (I 0x600E, SI 0x01)
Bit 1	Status Low Trip (I 0x600E S,I 0x02)
Bit 2	Status High Trip (I 0x600F, SI 0x01)
Bit 3	Status Low Trip (I 0x600F, SI 0x02)
Bit 4…31	0

5.6.19 Input Latch Local Timestamp

Index	SI	DataType	NV	Access	PM	Name
F6F0	0x01	UDINT		RO	tx	Input Latch Local Timestamp
	0x02	UDINT		RO	tx	Input Latch Local Timestamp

Subindex 0x01

Local controller time corresponding to the input latch time in microseconds. It starts at zero on device power-up. Mandatory if device has inputs. If device has no inputs defined, this corresponds the time immediately prior to writing to input SM.

Subindex 0x02

Local controller time corresponding to the input latch time in microseconds. It starts at zero on device power-up. Mandatory if device has inputs. If device has no inputs defined, this corresponds the time immediately prior to writing to input SM.

5.6.20 Configure Device

Index	SI	DataType	NV	Access	PM	Name
F840	0x01	UDINT	x	RW		Data Units
	0x03	Enum	x	RW		Data Units Enum

Subindex 0x01

Unit of the Value of the Analog Input Sensor Instance and all related parameters.

Trip Point Output All Instance	
0x00220000	Pascal
0xFD4E0000	mbar
0x00A10000	Torr

If this value is changed, also Subindex 3 will change the value accordingly.

Subindex 0x03

Data Unit for Input Sensor as Enum to have a list of possible values.

Data Units	
0x01(Pa)	Pascal
0x04(mBar)	mbar
0x05(Torr)	Torr

If this value is changed, also Subindex 1 will change the value accordingly.

5.6.21 Information Device

Index	SI	DataType	NV	Access	PM	Name
F940	0x01	UDINT		RO		Measurement Principle
	0x02	BYTE		RO		Number of Sensors
F9F0		V_STRING		RO		Manufacturer Serial Number
F9F1	0x01	UDINT		RO		CDP Functional Generation Number
F9F2	0x01	UDINT		RO		SDP Functional Generation Number (Module 1)
	0x02	UDINT		RO		SDP Functional Generation Number (Module 2)
F9F3		V_STRING		RO		Vendor Name
F9F4	0x01	V_STRING		RO		Semiconductor SDP Device Name (Module 1)
	0x02	V_STRING		RO		Semiconductor SDP Device Name (Module 2)
F9F5	0x01	USINT		RW	rx tx	Output Identifier
	0x02	USINT		RW	rx tx	Output Identifier
F9F6		UDINT		RO		Time since power on
F9F7		UDINT	x	RO		Total time powered
F9F8		UDINT		RO		Firmware Update Functional Generation Number

Subindex 0x01 (F940)

Measurement principle assigned to the object instance.

The most significant nibble of the parameter represents the sensor type of the first Module, the second most significant nibble of the parameter represents the sensor type of the second Module, and so forth.

Measurement Principle (Index F940)	
1	Capacitance Manometer
2	Piezo
3	Heat Transfer
4	Cold Cathode
5	Hot Cathode

Subindex 0x02 (F940)

Number of Sensors (Index F940): In this device are 2 sensors implemented.

5.6.22 Command Zero Adjust

Execution of this command will start a Zero Adjust operation.

Index	SI	DataType	NV	Access	PM	Name
FB40	0x01	O_STRING		RW		Command
	0x02	BYTE		RO		Status
	0x03	O_STRING(3)		RO		Response

Subindex 0x01

A zero adjust command is initiated when the following byte sequence is sent.

Command	
Byte 0	0: Zero Adjust
Byte 1	Index of the Sensor Module. Value has to be 1 1: Heat Transfer
Byte 2…5	Zero Adjust value (Data format: REAL). Value has to be 0

Subindex 0x02

Status (supported values)	
0	Last command completed, no errors, no reply available
1	Last command completed, no errors, reply available
2	Last command completed, errors present, no reply available
3	Last command completed, errors present, reply available
255	Command is executing

Subindex 0x03

Response	
Byte 0	See Subindex 0x02
Byte 1	not used = 0x00
Byte 2	0: Zero Adjust successful 1: Zero Adjust failed: out-of-range 254: No previous Zero Adjust command issued

5.6.23 Command Full Scale Adjust

Execution of this command will start a Full Scale Adjust operation.

Index	SI	DataType	NV	Access	PM	Name
FB41	0x01	O_STRING		RW		Command
	0x02	BYTE		RO		Status
	0x03	O_STRING(3)		RO		Response

Subindex 0x01

A full scale adjust command is initiated when the following byte sequence is sent.

Command	
Byte 0	0: Full Scale Adjust
Byte 1	Index of the Sensor Module. Value has to be 1 1: Heat Transfer
Byte 2…5	Full Scale value (Data format: REAL). Value has to be 0

Subindex 0x02

Status (supported values)	
0	Last command completed, no errors, no reply available
1	Last command completed, no errors, reply available
2	Last command completed, errors present, no reply available
3	Last command completed, errors present, reply available
255	Command is executing

Subindex 0x03

Response	
Byte 0	See Subindex 0x02
Byte 1	not used = 0x00
Byte 2	0: Full Scale Adjust successful 1: Full Scale Adjust failed: out-of-range 254: No previous Full Scale Adjust command issued

5.6.24 Command Degas ON / OFF

Execution of this command will initiate or cancel a degas operation.

Index	SI	DataType	NV	Access	PM	Name
FB43	0x01	O_STRING(2)		RW		Command
	0x02	BYTE		RO		Status
	0x03	O_STRING(3)		RO		Response

Subindex 0x01

A degas command is initiated when the following byte sequence is sent.

Command	
Byte 0	0: Degas OFF 1: Degas ON
Byte 1	Index of the sensor module. Value has to be 2 2: Hot Cathode

Subindex 0x02

Status (supported values)	
0	Last command completed, no errors, no reply available
1	Last command completed, no errors, reply available
2	Last command completed, errors present, no reply available
3	Last command completed, errors present, reply available
255	Command is executing

Subindex 0x03

Response	
Byte 0	See Subindex 0x02
Byte 1	not used = 0x00
Byte 2	0: Degas ON / OFF successful 1: Degas ON / OFF failed (unspecified reason) 2: Degas On failed because pressure to high 254: No previous Degas ON / OFF command issued

5.6.25 Command Emission ON / OFF

Execution of this command will turn on or off the gauge's emission state.

Index	SI	DataType	NV	Access	PM	Name
FB44	0x01	O_STRING(2)		RW		Command
	0x02	BYTE		RO		Status
	0x03	O_STRING(3)		RO		Response

Subindex 0x01

An emission command is initiated when the following byte sequence is sent.

Command	
Byte 0	0: Emission OFF 1: Emission ON
Byte 1	Index of the sensor module. Value has to be 2 2: Hot Cathode

Subindex 0x02

Status (supported values)	
0	Last command completed, no errors, no reply available
1	Last command completed, no errors, reply available
2	Last command completed, errors present, no reply available
3	Last command completed, errors present, reply available
255	Command is executing

Subindex 0x03

Response	
Byte 0	See Subindex 0x02
Byte 1	not used = 0x00
Byte 2	0: Emission ON / OFF successful 1: Emission ON / OFF failed (unspecified reason) 2: Emission On failed because pressure to high 254: No previous Emission ON / OFF command issued

5.6.26 Device Reset Command

Execution of this command causes the device to emulate a complete power cycle. This includes an ESC reset. An SDP may limit some behavior of the power cycle emulation, but shall not exclude the EtherCAT interface.

As consequence of an ESC reset all following devices are disconnected from the network.

There are two versions of this command:

- Standard reset (as described above)
- Factory reset (as described above, but additionally, all parameters are restored to as-shipped defaults).

Index	SI	DataType	NV	Access	PM	Name
FBF0	0x01	O_STRING(6)		RW		Command
	0x02	BYTE		RO		Status
	0x03	O_STRING(2)		RO		Response

Subindex 0x01

A device reset is initiated when the following byte sequence is sent.

Command	
Byte 0	0x74
Byte 1	0x65
Byte 2	0x73
Byte 3	0x65
Byte 4	0x72
Byte 5	0x00 = Standard reset, 0x66 = Factory Reset

Subindex 0x02

Status (supported values)	
0	Reserved
1	Reserved
2	Last command completed, error, no response
3	Reserved
255	Command is executing

Subindex 0x03

Response	
Byte 0	See Subindex 0x02
Byte 1	not used = 0x00

5.6.27 Exception Reset Command

Execution of this command clears the latched exceptions.

Index	SI	DataType	NV	Access	PM	Name
FBF1	0x01	O_STRING(5)		RW		Command
	0x02	BYTE		RO		Status
	0x03	O_STRING(2)		RO		Response

Subindex 0x01

An exception reset is initiated when the following byte sequence is sent.

Command	
Byte 0	0x74
Byte 1	0x65
Byte 2	0x73
Byte 3	0x65
Byte 4	0x72

Subindex 0x02

Status (supported values)	
0	Last command completed, no error, no response
1	Reserved
2	Last command completed, error, no response
3	Reserved
255	Command is executing

Subindex 0x03

Response	
Byte 0	See Subindex 0x02
Byte 1	not used = 0x00

5.6.28 Store Parameters Command

Execution of this command will store all parameters to non-volatile memory. If a device automatically saves all non-volatile parameters at the time they are set, this command will not take any action.

Index	SI	DataType	NV	Access	PM	Name
FBF2	0x01	O_STRING(4)		RW		Command
	0x02	BYTE		RO		Status
	0x03	O_STRING(2)		RO		Response

Subindex 0x01

A device reset is initiated when the following byte sequence is sent.

Read:

Command: Read	
Byte 0	0x01 = slave saves the non-volatile parameters when writing 0xFBF2:01 with 0x65766173
Byte 1	not used = 0x00
Byte 2	not used = 0x00
Byte 3	not used = 0x00

Write:

Command: Write	
Byte 0	0x73
Byte 1	0x61
Byte 2	0x76
Byte 3	0x65

Subindex 0x02

Status (supported values)	
0	Last command completed, no error, no response
1	Reserved
2	Last command completed, error, no response
3	Reserved
255	Command is executing

Subindex 0x03

Response	
Byte 0	See Subindex 0x02
Byte 1	not used = 0x00

5.6.29 Calculate Checksum Command

Execution of this command will calculate a checksum for all writable, non-volatile parameters as currently stored in non-volatile memory.

Index	SI	DataType	NV	Access	PM	Name
FBF3	0x01	O_STRING(4)		RW		Command
	0x02	BYTE		RO		Status
	0x03	O_STRING(6)		RO		Response

Subindex 0x01

A device reset is initiated when the following byte sequence is sent.

Read

Command: Read	
Byte 0	Bit 0 = 1: non-volatile parameters supported Bit 1 = 1: CRC-32 Bit 2..7 = 0: not used
Byte 1	not used = 0x00
Byte 2	not used = 0x00
Byte 3	not used = 0x00

Write

Command: Write	
Byte 0	Bit 0 = 1: use default checksum algorithm of the slave Bit 1 = 1: CRC-32 Bit 2..7 = 0: not used
Byte 1	not used = 0x00
Byte 2	not used = 0x00
Byte 3	not used = 0x00

Subindex 0x02

Status (supported values)	
0	Last command completed, no error, no response
1	Reserved
2	Last command completed, error, no response
3	Reserved
255	Command is executing

Subindex 0x03

Response	
Byte 0	See Subindex 0x02
Byte 1	not used = 0
Byte 2	Checksum return value, Byte 0
Byte 3	Checksum return value, Byte 1
Byte 4	Checksum return value, Byte 2
Byte 5	Checksum return value, Byte 3

5.6.30 Load Parameters Command

Execution of this command will load all parameters from non-volatile memory.

Index	SI	DataType	NV	Access	PM	Name
FBF4	0x01	O_STRING(4)		RW		Command
	0x02	BYTE		RO		Status
	0x03	O_STRING(2)		RO		Response

Subindex 0x01

A device reset is initiated when the following byte sequence is sent.

Read:

Command: Read	
Byte 0	0x01 = slave loads the non-volatile parameters when writing 0xFBF4:01 with 0x64616F6C
Byte 1	not used = 0x00
Byte 2	not used = 0x00
Byte 3	not used = 0x00

Write:

Command: Write	
Byte 0	0x6C
Byte 1	0x6F
Byte 2	0x61
Byte 3	0x64

Subindex 0x02

Status (supported values)	
0	Last command completed, no error, no response
1	Reserved
2	Last command completed, error, no response
3	Reserved
255	Command is executing

Subindex 0x03

Response	
Byte 0	See Subindex 0x02
Byte 1	not used = 0x00

6 BCG552: Object Structure

This chapter describes the CANopen over EtherCAT (CoE) Object Dictionary.

6.1 Object Dictionary structure

The objects in the CoE Object Dictionary can be accessed with SDO services, and many of the dictionary objects can be mapped for cyclic communication in PDO's. Each object is addressed using a 16-bit index and an 8-bit subindex.

The following table presents the overall layout of the standard Object Dictionary.

Index (hex.)	Object dictionary area	
1000 – 1FFF	Communication profile area	
2000 – 5FFF	Manufacturer-specific profile area	
6000 – 6FFF	Profile Specific Area	Input area
7000 – 7FFF		Output area
8000 – 8FFF		Configuration area
9000 – 9FFF		Information area
A000 – AFFF		Diagnosis area
B000 – BFFF		Service Transfer area
C000 – EFFF		Reserved area
F000 – FFFF		Device area

Explanations for the abbreviations in the columns of the tables are given below:

Abbr.	Description
Access	SDO read/write access • RO: object can only be read by the SDO service • RW: object can be both read and written by the SDO service
CoE	CAN application protocol over EtherCAT
Index	Object Index (hex.) (address of an object)
NV	Nonvolatile; attribute value is maintained through power cycles
Object	Abstract representation of a particular component within a device, which consists of data, parameters, and methods.
PDO	Process Data Object. Structure described by mapping parameters containing one or several process data entities.
PM	PDO mapping • Rx: object can be mapped into an Rx PDO • Tx : object can be mapped into a Tx PDO
RxPDO	Receive PDO. A Process Data Object received by an EtherCAT slave.
SDO	Service Data Objects. CoE asynchronous mailbox communications where all objects in the Object Dictionary can be read and written.
SI	Subindex (hex.) (sub-address of an object)
Type	Data Type • BOOL, BIT = 1 bit. Boolean (0 = false, 1 = true) • USINT, BYTE = 8 bit. Unsigned Byte • UINT = 16 bit. Unsigned integer value • UDINT = 32 bit. Unsigned integer value • ULINT = 64 bit. Unsigned integer value • REAL = 32 bit. Floating point • V_STRING = 8×n bit. Visible string (1 byte for character) • O_STRING = 8xn bit. Octet string (1 byte for element)
TxPDO	Transmit PDO. A Process Data Object sent from an EtherCAT slave.

6.2 Communication Profile Objects (0x1000…0x1FFF)

The objects of the communication profile describe the basic EtherCAT properties of the BCG552 and are common to all EtherCAT slaves using the CoE communication protocol. The objects are described in following table:

Index	SI	DataType	NV	Access	PM	Name
1000		UDINT		RO		Device Type 0x0000138B => 0x138B = dec 5003
1008		V_STRING		RO		Manufacturer Device name
1009		V_STRING		RO		Manufacturer Hardware Version
100A		V_STRING		RO		Manufacturer Software Version
100B		V_STRING		RO		Manufacturer Bootloader Version
1018				RO		Identity Object
	0x01	UDINT		RO		Vendor ID
	0x02	UDINT		RO		Product Code
	0x03	UDINT		RO		Revision Number
	0x04	UDINT		RO		Serial Number
10F8		ULINT		RO		Timestamp Object

6.2.1 Process Data Objects (PDO's)

The BCG552 consists of three vacuum pressure sensors. The characteristic of this combo device is that only one vacuum pressure sensor outputs an actual pressure value at one time. The other sensor is in overrange condition which means that the pressure is higher than the measurement range of the sensor or underrange condition which means that the pressure is lower than the measurement of the sensor. The 'Combination Gauge Active Value' outputs the pressure value form the active measuring sensor.
For each sensor module a default mapping is configured. The mapping for each sensor module has the same contents. For a compact cyclic data frame duplicated mappings can be deactivated.

Or to meet other requirements the TxPDO's 1A01, 1A03, 1A05 or 1A07 and the RxPDO 1601 are designated for user mapping. These PDO's do not have default values and can be set up by the PDO configuration.

RxPDO's

Index	SI	DataType	NV	Access	PM	Name
1600		PM		RW		RxPDO Receive PDO Mapping,
1601		PM		RW		RxPDO Receive PDO Mapping, User Mapping

TxPDO's

Index	SI	DataType	NV	Access	PM	Name
1A00		PM		RW		TxPDO Transmit PDO Mapping
1A01		PM		RW		TxPDO Transmit PDO Mapping, User Mapping
1A02		PM		RW		TxPDO Transmit PDO Mapping
	0x01	UDINT				0x60120101 for Reading Valid
	0x02	UDINT				0x60120201 for Overrange Exceeded
	0x03	UDINT				0x60120301 for Underrange Exceeded
	0x04	UDINT				0x00000005 for Padding Bits 1 (5 bit)
	0x05	UDINT				0x60101132 for Sensor Value
1A03		PM		RW		TxPDO Transmit PDO Mapping, User Mapping
1A04		PM		RW		TxPDO Transmit PDO Mapping Combination Gauge
1A05		PM		RW		TxPDO Transmit PDO Mapping, User Mapping
1A06		PM		RW		TxPDO Transmit PDO Mapping
1A07		PM		RW		TxPDO Transmit PDO Mapping, User Mapping
1BFE		PM		RW		Transmit PDO Mapping
	0x01	UDINT				0xF3800008 for Active Exception Status
	0x02	UDINT				0xF6400101 for Combination Gauge Reading Valid
	0x03	UDINT				0xF6400201 for Combination Gauge Overrange Exceeded
	0x04	UDINT				0xF6400301 for Combination Gauge Underrange Exceeded
	0x05	UDINT				0x00000005 for Padding Bits 1 (5 Bit)
	0x06	UDINT				0xF6401216 for Combination Gauge Active Value
	0x07	UDINT				0xF6401132 for Combination Gauge Active Sensor Number
	0x08	UDINT				0xF6410132 for Trip Point Output All Instance
1BFF		PM		RW		TxPDO Transmit PDO Mapping Device, User Mapping
1C00	0x01 0x02 0x03 0x04	BYTE		RW		Sync Manager Type
1C12 / 1C13	0x01 0x02 0x03 0x04	UINT		RW		Sync Manager PDO Assignment
1C32 / 1C33	0x01 - 0x20			RW		Sync Manager Parameter

6.3 Input Area (0x6000…0x6FFF)

6.3.1 Input Common Capacitance Diaphragm

Index	SI	DataType	NV	Access	PM	Name
6000	0x0E	BOOL		RO	tx	TxPdoState
	0x11	REAL		RO	tx	Sensor Value

Subindex 0x0E

Is set if the device is not in Safe State (value (I 0x6nn0, SI 0x11) = valid)

TxPdoState	
0	Invalid
1	Valid

Subindex 0x11

The corrected, converted, calibrated final analog input value of the sensor.

6.3.2 Input Capacitance Diaphragm

Index	SI	DataType	NV	Access	PM	Name
6001	0x01	BOOL		RO	tx	Reading Valid
	0x02	BOOL		RO	tx	Overrange Exceeded
	0x03	BOOL		RO	tx	Underrange Exceeded

Subindex 0x01

Indicates whether the Value parameter contains a valid value within the specified accuracy or not.

Reading Valid	
0	Invalid
1	Valid

Subindex 0x02

Indicates whether the Value parameter contains a value in overrange.

Overrange Exceeded	
0	No Overrange Exceeded
1	Overrange Exceeded

Subindex 0x03

Indicates whether the Value parameter contains a value in underrange.

Underrange Exceeded	
0	No Underrange Exceeded
1	Underrange Exceeded

6.3.3 Input Common Piezo

Index	SI	DataType	NV	Access	PM	Name
6010	0x0E	BOOL		RO	tx	TxPdoState
	0x11	REAL		RO	tx	Sensor Value

Subindex 0x0E

Is set if the device is not in Safe State (value (I 0x6010, SI 0x11) = valid).

TxPdoState	
0	Invalid
1	Valid

Subindex 0x11

The corrected, converted, calibrated final analog input value of the sensor.

6.3.4 Input Piezo

Index	SI	DataType	NV	Access	PM	Name
6012	0x01	BOOL		RO	tx	Reading Valid
	0x02	BOOL		RO	tx	Overrange Exceeded
	0x03	BOOL		RO	tx	Underrange Exceeded

Subindex 0x01

Indicates whether the Value parameter contains a valid value within the specified accuracy or not.

Reading Valid	
0	Invalid
1	Valid

Subindex 0x02

Indicates whether the Value parameter contains a value in overrange.

Overrange Exceeded	
0	No Overrange Exceeded
1	Overrange Exceeded

Subindex 0x03

Indicates whether the Value parameter contains a value in underrange.

Underrange Exceeded	
0	No Underrange Exceeded
1	Underrange Exceeded

6.3.5 Input Common Heat Transfer

Index	SI	DataType	NV	Access	PM	Name
6020	0x0E	BOOL		RO	tx	TxPdoState
	0x11	REAL		RO	tx	Sensor Value

Subindex 0x0E

Is set if the device is not in Safe State (value (I 0x6020, SI 0x11) = valid).

TxPdoState	
0	Invalid
1	Valid

Subindex 0x11

The corrected, converted, calibrated final analog input value of the sensor.

6.3.6 Input Heat Transfer

Index	SI	DataType	NV	Access	PM	Name
6023	0x01	BOOL		RO	tx	Reading Valid
	0x02	BOOL		RO	tx	Overrange Exceeded
	0x03	BOOL		RO	tx	Underrange Exceeded

Subindex 0x01

Indicates whether the Value parameter contains a valid value within the specified accuracy or not.

Reading Valid	
0	Invalid
1	Valid

Subindex 0x02

Indicates whether the Value parameter contains a value in overrange.

Overrange Exceeded	
0	No Overrange Exceeded
1	Overrange Exceeded

Subindex 0x03

Indicates whether the Value parameter contains a value in underrange.

Underrange Exceeded	
0	No Underrange Exceeded
1	Underrange Exceeded

6.3.7 Input Common Hot Cathode Ion

Index	SI	DataType	NV	Access	PM	Name
6030	0x0E	BOOL		RO	tx	TxPdoState
	0x11	REAL		RO	tx	Sensor Value

Subindex 0x0E

Is set if the device is not in Safe State (value (I 0x6020, SI 0x11) = valid).

TxPdoState	
0	Invalid
1	Valid

Subindex 0x11

The corrected, converted, calibrated final analog input value of the sensor.

6.3.8 Input Hot Cathode Ion

Index	SI	DataType	NV	Access	PM	Name
6035	0x01	BOOL		RO	tx	Reading Valid
	0x02	BOOL		RO	tx	Overrange Exceeded
	0x03	BOOL		RO	tx	Underrange Exceeded
	0x05	BOOL		RO	tx	Emission Status Off/On
	0x06	BOOL		RO	tx	Degas Status Off/On

Subindex 0x01

Indicates whether the Value parameter contains a valid value within the specified accuracy or not.

Reading Valid	
0	Invalid
1	Valid

Subindex 0x02

Indicates whether the Value parameter contains a value in overrange.

Overrange Exceeded	
0	No Overrange Exceeded
1	Overrange Exceeded

Subindex 0x03

Indicates whether the Value parameter contains a value in underrange.

Underrange Exceeded	
0	No Underrange Exceeded
1	Underrange Exceeded

Subindex 0x05

Emission Status Off/On	
0	OFF
1	ON

Subindex 0x06

Degas Status Off/On	
0	OFF
1	ON

6.3.9 Input Trip Point 1

Index	SI	DataType	NV	Access	PM	Name
600E	0x01	BOOL		RO	tx	Status High Trip
	0x02	BOOL		RO	tx	Status Low Trip

Subindex 0x01

Status High Trip	
0	High Trip not assert
1	High Trip assert

Subindex 0x02

Status Low Trip	
0	Low Trip not assert
1	Low Trip assert

6.3.10 Input Trip Point 2

Index	SI	DataType	NV	Access	PM	Name
600F	0x01	BOOL		RO	tx	Status High Trip
	0x02	BOOL		RO	tx	Status Low Trip

Subindex 0x01

Status High Trip	
0	High Trip not assert
1	High Trip assert

Subindex 0x02

Status Low Trip	
0	Low Trip not assert
1	Low Trip assert

6.4 Configuration Area (0x8000…0x8FFF)

6.4.1 Configuration Hot Cathode Ion

Index	SI	DataType	NV	Access	PM	Name
8035	0x01	BOOL	x	RW		Filament User Mode
	0x02	BOOL	x	RW		Emission User Mode
	0x11	USINT	x	RW		Active Filament
	0x13	REAL	x	RW		Emission Current

Subindex 0x01

Defines whether the filament is switched automatically (automatic) or manually by the user (manual).
Defines whether the filament selection is static as defined by "Active Filament" (manual) or the active filament is changed always when the filament is switched on (automatic).

Filament User Mode	
0	Automatic
1	Manual

Subindex 0x02

Defines whether the emission is switched on automatically (controlled by a different sensor) (automatic) or manually by the user (manual).

Emission User Mode	
0	Automatic
1	Manual

Subindex 0x11

Active Sensor filament.

Active Filament	
Bit 0	Filament 1 is on if Bit is set
Bit 1	Filament 2 is on if Bit is set
Bit 2…7	Always 0 (reserved)

Subindex 0x13

Emission current in milliamps.

6.4.2 Configuration Trip Point 1

If High Trip Source Index is 0x60101100.

The High Trip Point is calculated by:

$$\text{High Trip Point Limit} = \text{Value}^{*)} \times \text{Percentage}^{**)}$$

*) Value from Piezo Sensor (I: 0x6010, SI: 0x11).

**) Percentage High Trip Source (I: 0x800E/F, SI: 0x13).

In this case, the High Trip Point Limit value is automatically updated by the device itself. Any user-written value to the parameter High Trip Point Limit will be refused with an abort code.

If High Trip Source Index is 0x800E1100 or 0x800F1100 the High Trip Point is equal with the value referenced in High Trip Point Limit.

The value defined in High Trip Point Limit is compared with the pressure value referenced by the Source Index parameter.

If Low Trip Source Index is 0x60101100

The Low Trip Point is calculated by:

$$\text{Low Trip Point Limit} = \text{Value}^{*)} \times \text{Percentage}^{**)}$$

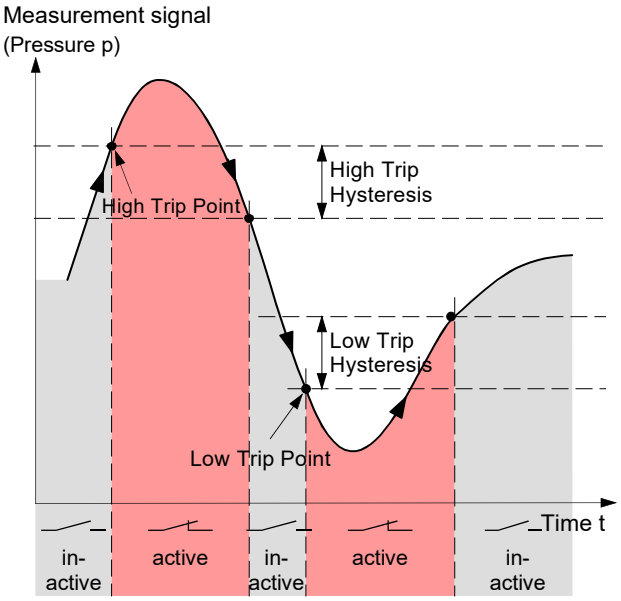
*) Value from Piezo Sensor (I: 0x6010, SI: 0x11).

**) Percentage Low Trip Source (I: 0x800E/F, SI: 0x16).

In this case, the Low Trip Point Limit value is automatically updated by the device itself. Any user-written value to the parameter Low Trip Point Limit will be refused with an abort code.

If Low Trip Source Index is 0x800E1400 or 0x800F1400 the Low Trip Point is equal with the value referenced in Low Trip Point Limit.

The value defined in Low Trip Point Limit is compared with the pressure value referenced by the Source Index parameter.



Index	SI	DataType	NV	Access	PM	Name
800E	0x01	BOOL	x	RW		High Trip Enable
	0x02	BOOL	x	RW		Low Trip Enable
	0x11	REAL	x	RW		High Trip Point Limit
	0x12	UDINT	x	RW		High Trip Source Index
	0x13	REAL	x	RW		Percentage High Trip Source
	0x14	REAL	x	RW		Low Trip Point Limit
	0x15	UDINT	x	RW		Low Trip Source Index
	0x16	REAL	x	RW		Percentage Low Trip Source
	0x17	REAL	x	RW		High Trip Hysteresis
	0x18	REAL	x	RW		Low Trip Hysteresis
	0x1A	UDINT	x	RW		Source Index

Subindex 0x01

High Trip Point Enable	
0	Disable
1	Enable

Subindex 0x02

Low Trip Point Enable	
0	Disable
1	Enable

Subindex 0x11

High Trip Point Limit: High limit to trigger trip point condition if Input Value (I 0x900E, SI 0x01) is above this limit.

Subindex 0x12

Object index of High Trip Point Value source.

Bit 16…31: Index
Bit 08…15: Subindex
Bit 00…07: reserved

It is possible to reference to "High Trip Point Limit" or to the sensor value from the Piezo Sensor (I 0x6010, SI 0x11).

Subindex 0x13

Percentage of Value referenced by High Trip Source Index (I 0x6010, SI 0x11) in [%]. If High Trip Source Index is I 0x800E, SI 0x12 this parameter is not used.

Subindex 0x14

Low Trip Point Limit: Low limit to trigger trip point condition if Input Value (I 0x900E, SI 0x01) is below this limit.

Subindex 0x15

Object index of Low Trip Point Value source. Index of Low Trip Point Limit (I 0x800E, SI 0x14)

Bit 16…31: Index
Bit 08…15: Subindex
Bit 00…07: reserved

It is possible to reference to "Low Trip Point Limit" or to the sensor value from the Piezo Sensor (I 0x6010, SI 0x11).

Subindex 0x16

Percentage of Value referenced by Low Trip Source Index (I 0x6010, SI 0x11) in [%]. If Low Trip Source Index is I 0x800E, SI 0x14 this parameter is not used.

Subindex 0x17

High Trip Hysteresis: Hysteresis value for High Trip Point.

Subindex 0x18

Low Trip Hysteresis: Hysteresis value for Low Trip Point.

Subindex 0x1A

Object index of active source of (I 0xF640 SI 0x11) Input Value.

Source Index	
Bit 16…31	Index
Bit 08…15	Subindex
Bit 00…07	Reserved

6.4.3 Configuration Trip Point 2

Index	SI	DataType	NV	Access	PM	Name
800F	0x01	BOOL	x	RW		High Trip Enable
	0x02	BOOL	x	RW		Low Trip Enable
	0x11	REAL	x	RW		High Trip Point Limit
	0x12	UDINT	x	RW		High Trip Source Index
	0x13	REAL	x	RW		Percentage High Trip Source
	0x14	REAL	x	RW		Low Trip Point Limit
	0x15	UDINT	x	RW		Low Trip Source Index
	0x16	REAL	x	RW		Percentage Low Trip Source
	0x17	REAL	x	RW		High Trip Hysteresis
	0x18	REAL	x	RW		Low Trip Hysteresis
	0x1A	UDINT	x	RW		Source Index

Subindex 0x01

High Trip Point Enable	
0	Disable
1	Enable

Subindex 0x02

Low Trip Point Enable	
0	Disable
1	Enable

Subindex 0x11

High Trip Point limit: High limit to trigger trip point condition if Input Value (I 0x900F, SI 0x01) is above this limit.

Subindex 0x12

Object index of High Trip Point Value source

Bit 16…31: Index
Bit 08…15: Subindex
Bit 00…07: reserved

It is possible to reference to "High Trip Point Limit" or to the sensor value from the Piezo Sensor (I 0x6010, SI 0x11).

Subindex 0x13

Percentage of Value referenced by High Trip Source Index (I 0x6010, SI 0x11) in [%]. If High Trip Source Index is I 0x800F, SI 0x12 this parameter is not used.

Subindex 0x14

Low Trip Point Limit: Low limit to trigger trip point condition if Input Value (I 0x900F, SI 0x01) is below this limit.

Subindex 0x15

Object index of Low Trip Point Value source. Index of Low Trip Point Limit (I 0x800F, SI 0x14).

Bit 16…31: Index
Bit 08…15: Subindex
Bit 00…07: reserved

It is possible to reference to "Low Trip Point Limit" or to the sensor value from the Piezo Sensor (I 0x6010, SI 0x11).

Subindex 0x16

Percentage of Value referenced by Low Trip Source Index (I 0x6010, SI 0x11) in [%].If Low Trip Source Index is I 0x800F, SI 0x14 this parameter is not used.

Subindex 0x17

High Trip Hysteresis: Hysteresis value for High Trip Point.

Subindex 0x18

Low Trip Hysteresis: Hysteresis value for Low Trip Point.

Subindex 0x1A

Object index of active source of (I 0xF640 SI 0x11) Input Value.

Source Index	
Bit 16…31	Index
Bit 08…15	Subindex
Bit 00…07	Reserved

6.5 Information Area (0x9000…0x9FFF)

The Information Data object defines the input process data.

6.5.1 Information Capacitance Diaphragm

Index	SI	DataType	NV	Access	PM	Name
9001	0x01	UINT		RO		Sensor Warning
	0x02	UINT		RO		Sensor Error

Subindex 0x01

Sensor Warnings	
Bit 0…15	0

Subindex 0x02

Sensor Errors	
Bit 0	0
Bit 1	Electronics Failure
Bit 2…15	0

6.5.2 Information Piezo

Index	SI	DataType	NV	Access	PM	Name
9012	0x01	UINT		RO		Sensor Warning
	0x02	UINT		RO		Sensor Error

Subindex 0x01

Sensor Warnings	
Bit 0…15	0

Subindex 0x02

Sensor Errors	
Bit 0	0
Bit 1	Electronics Failure
Bit 2…15	0

6.5.3 Information Heat Transfer

Index	SI	DataType	NV	Access	PM	Name
9023	0x01	UINT		RO		Sensor Warning
	0x02	UINT		RO		Sensor Error

Subindex 0x01

Sensor Warnings	
Bit 0…15	0

Subindex 0x02

Sensor Errors	
Bit 0	0
Bit 1	Electronics Failure
Bit 2…15	0

6.5.4 Information Hot Cathode Ion

Index	SI	DataType	NV	Access	PM	Name
9035	0x01	UINT		RO		Sensor Warning
	0x02	UINT		RO		Sensor Error

Subindex 0x01

Sensor Warnings	
Bit 0…15	0

Subindex 0x02

Sensor Errors	
Bit 0	Sensor Filament 1 Error
Bit 1	Sensor Filament 2 Error
Bit 2…8	0
Bit 9	Electronics Failure
Bit 10	Over Temperature of Electronics
Bit 11…15	0

6.5.5 Information Trip Point 1/2

Index	SI	DataType	NV	Access	PM	Name
900E	0x01	REAL		RO		Input value Trip Point 1
900F	0x01	REAL		RO		Input value Trip Point 2

Subindex 0x1(900E)

Input Value Trip Point 1: Trip Point Input value as referenced by Source Index (I 0x800E, SI 0x1A).

Subindex 0x1(900F)

Input Value Trip Point 2: Trip Point Input value as referenced by Source Index (I 0x800F, SI 0x1A).

6.6 Device Area (0xF000...0xAFFF)

6.6.1 Semiconductor Device Profile

Index	SI	DataType	NV	Access	PM	Name
F000	0x01	UINT		RO		Index Distance
	0x02	UINT		RO		Maximum Number of Modules

Subindex 0x01

Index Distance: Index offset between PDO entries of two consecutive modules (for ETG.5003 = 0x10), e.g. 0x6000, 0x6010.

Subindex 0x02

Maximum Number of Modules: For the BCG552 this value always is 4.

6.6.2 Module Profile List

Index	SI	DataType	NV	Access	PM	Name
F010	0x01	UDINT		RO		Module Profile List
	0x02	UDINT		RO		Module Profile List
	0x03	UDINT		RO		Module Profile List
	0x04	UDINT		RO		Module Profile List

Subindex 0x01

Each sub-index lists the profile-number of the corresponding module.

Subindex 0x02

Each sub-index lists the profile-number of the corresponding module.

Subindex 0x03

Each sub-index lists the profile-number of the corresponding module.

Subindex 0x04

Each sub-index lists the profile-number of the corresponding module.

6.6.3 Exceptions

6.6.4 Active Exception Status

Index	SI	DataType	NV	Access	PM	Name
F380		USINT		RO	tx	ActiveException Status

Active Exception Status

Active Exception Status	
Bit 0	Device Warning
Bit 1	Manufacturer Warning
Bit 2	Device Error
Bit 3	Manufacturer Error
Bit 4…7	0

6.6.5 Active Device Warning Details

The "active device warning details" parameter describes the warning state of the complete device.

Index	SI	DataType	NV	Access	PM	Name
F381	0x01	UDINT		RO	tx	Active Device Warning Details
	0x02	UDINT		RO	tx	Active Device Warning Details
	0x03	UDINT		RO	tx	Active Device Warning Details
	0x04	UDINT		RO	tx	Active Device Warning Details
F382	0x01	UDINT		RO	tx	Active Manufacturer Warning Details
	0x02	UDINT		RO	tx	Active Manufacturer Warning Details
	0x03	UDINT		RO	tx	Active Manufacturer Warning Details
	0x04	UDINT		RO	tx	Active Manufacturer Warning Details

Subindex 0x01

Active Device Warning Details (Index F381)	
Bit 0…31	0

Subindex 0x02

Active Device Warning Details (Index F381)	
Bit 0…31	0

Subindex 0x03

Active Device Warning Details (Index F381)	
Bit 0…31	0

Subindex 0x04

Active Device Warning Details (Index F381)	
Bit 0…31	0

Subindex 0x01

Active Manufacturer Warning Details (Index F382)	
Bit 0…31	0

Subindex 0x02

Active Manufacturer Warning Details (Index F382)	
Bit 0…31	0

Subindex 0x03

Active Manufacturer Warning Details (Index F382)	
Bit 0…31	0

Subindex 0x04

Active Manufacturer Warning Details (Index F382)	
Bit 0…31	0

6.6.6 Active Device Error Details

The "active device error details" parameter describes the error state of the complete device.

Index	SI	DataType	NV	Access	PM	Name
F383	0x01	UDINT		RO	tx	Active Device Error Details
	0x02	UDINT		RO	tx	Active Device Error Details
	0x03	UDINT		RO	tx	Active Device Error Details
	0x04	UDINT		RO	tx	Active Device Error Details
F384	0x01	UDINT		RO	tx	Active Manufacturer Error Details
	0x02	UDINT		RO	tx	Active Manufacturer Error Details
	0x03	UDINT		RO	tx	Active Manufacturer Error Details
	0x04	UDINT		RO	tx	Active Manufacturer Error Details

Subindex 0x01

Active Device Error Details (Index F383; Capacitance Diaphragm)	
Bit 0	0
Bit 1	Electronics failure
Bit 2…31	0

Subindex 0x02

Active Device Error Details (Index F383; Piezo)	
Bit 0	0
Bit 1	Electronics failure
Bit 2…31	0

Subindex 0x03

Active Device Error Details (Index F383; Heat Transfer)	
Bit 0	0
Bit 1	Electronics failure
Bit 2…31	0

Subindex 0x04

Active Device Error Details (Index F383; Hot Cathode)	
Bit 0	Sensor Filament 1 Error
Bit 1	Sensor Filament 2 Error
Bit 2…8	0
Bit 9	Electronics Failure
Bit 10	Over Temperature of Electronics
Bit 11…15	0

Subindex 0x01

Active Manufacturer Error Details (Index F384)	
Bit 0…31	0

Subindex 0x02

Active Manufacturer Error Details (Index F384)	
Bit 0…31	0

Subindex 0x03

Active Manufacturer Error Details (Index F384)	
Bit 0…31	0

Subindex 0x04

Active Manufacturer Error Details (Index F384)	
Bit 0…31	0

6.6.7 Active Global Device Warning Details

The "active global device warning details" parameter describes the warning state of the complete device.

Index	SI	DataType	NV	Access	PM	Name
F385	0x01	UDINT		RO	tx	Active Global Device Warning Details
F386	0x01	UDINT		RO	tx	Active Global Manufacturer Warning Details

Subindex 0x01

Active Global Device Warning Details (Index F385)	
Bit 0	0
Bit 1	uP exception
Bit 2	0
Bit 3	EEPROM exception
Bit 4…31	0

Subindex 0x01

Active Global Manufacturer Warning Details (Index F386)	
Bit 0…31	0

6.6.8 Active Global Device Error Details

The "active global device error details" parameter describes the error state of the complete device.

Index	SI	DataType	NV	Access	PM	Name
F387	0x01	UDINT		RO	tx	Active Global Device Error Details
F388	0x01	UDINT		RO	tx	Active Global Manufacturer Error Details

Subindex 0x01

Active Global Device Error Details (Index F387)	
Bit 0	0
Bit 1	uP exception
Bit 2	0
Bit 3	EEProm exception
Bit 4…31	0

Subindex 0x01

Active Global Manufacturer Error Details (Index F388)	
Bit 0…31	0

6.6.9 Latched Device Warning Details

Index	SI	DataType	NV	Access	PM	Name
F390		USINT		RO	tx	Latched Exceptions Status
F391	0x01	UDINT		RO	tx	Latched Device Warning Details
	0x02	UDINT		RO	tx	Latched Device Warning Details
	0x03	UDINT		RO	tx	Latched Device Warning Details
	0x04	UDINT		RO	tx	Latched Device Warning Details
F392	0x01	UDINT		RO	tx	Latched Manufacturer Warning Details
	0x02	UDINT		RO	tx	Latched Manufacturer Warning Details
	0x03	UDINT		RO	tx	Latched Manufacturer Warning Details
	0x04	UDINT		RO	tx	Latched Manufacturer Warning Details

Latched Exceptions Status

Latched version of 0xF380.

Subindex 0x01 (F391)

Latched Device Warning Details: Latched version of 0xF381:01.

Subindex 0x02 (F391)

Latched Device Warning Details: Latched version of 0xF381:02.

Subindex 0x03 (F391)

Latched Device Warning Details: Latched version of 0xF381:03.

Subindex 0x04 (F391)

Latched Device Warning Details: Latched version of 0xF381:04.

Subindex 0x01 (F392)

Latched Manufacturer Warning Details: Latched version of 0xF382:01.

Subindex 0x02 (F392)

Latched Manufacturer Warning Details: Latched version of 0xF382:02.

Subindex 0x03 (F392)

Latched Manufacturer Warning Details: Latched version of 0xF382:03.

Subindex 0x04 (F392)

Latched Manufacturer Warning Details: Latched version of 0xF382:04.

6.6.10 Latched Device Error Details

Index	SI	DataType	NV	Access	PM	Name
F393	0x01	UDINT		RO	tx	Latched Device Error Details
	0x02	UDINT		RO	tx	Latched Device Error Details
	0x03	UDINT		RO	tx	Latched Device Error Details
	0x04	UDINT		RO	tx	Latched Device Error Details
F394	0x01	UDINT		RO	tx	Latched Manufacturer Error Details
	0x02	UDINT		RO	tx	Latched Manufacturer Error Details
	0x03	UDINT		RO	tx	Latched Manufacturer Error Details
	0x04	UDINT		RO	tx	Latched Manufacturer Error Details

Subindex 0x01 (F393) Latched Device Error Details: Latched version of 0xF383:01.

Subindex 0x02 (F393) Latched Device Error Details: Latched version of 0xF383:02.

Subindex 0x03 (F393) Latched Device Error Details: Latched version of 0xF383:03.

Subindex 0x04 (F393) Latched Device Error Details: Latched version of 0xF383:04.

Subindex 0x01 (F394) Latched Manufacturer Error Details: Latched version of 0xF384:01.

Subindex 0x02 (F394) Latched Manufacturer Error Details: Latched version of 0xF384:02.

Subindex 0x03 (F394) Latched Manufacturer Error Details: Latched version of 0xF384:03.

Subindex 0x04 (F394) Latched Manufacturer Error Details: Latched version of 0xF384:04.

6.6.11 Latched Global Device Warning Details

Index	SI	DataType	NV	Access	PM	Name
F395	0x01	UDINT		RO	tx	Latched Global Device Warning Details
F396	0x01	UDINT		RO	tx	Latched Global Manufacturer Warning Details

Subindex 0x01 (F395) Latched Global Device Warning Details: Latched version of 0xF385:01.

Subindex 0x01 (F396) Latched Global Manufacturer Warning Details: Latched version of 0xF386:01.

6.6.12 Latched Global Device Error Details

Index	SI	DataType	NV	Access	PM	Name
F397	0x01	UDINT		RO	tx	Latched Global Device Error Details
F398	0x01	UDINT		RO	tx	Latched Global Manufacturer Error Details

Subindex 0x01 (F397) Latched Global Device Error Details: Latched version of 0xF387:01.

Subindex 0x01 (F398) Latched Global Manufacturer Error Details: Latched version of 0xF388:01.

6.6.13 Device Warning Mask

Index	SI	DataType	NV	Access	PM	Name
F3A1	0x01	UDINT	x	RW		Device Warning Mask
	0x02	UDINT	x	RW		Device Warning Mask
	0x03	UDINT	x	RW		Device Warning Mask
	0x04	UDINT	x	RW		Device Warning Mask
F3A2	0x01	UDINT	x	RW		Manufacturer Warning Mask
	0x02	UDINT	x	RW		Manufacturer Warning Mask
	0x03	UDINT	x	RW		Manufacturer Warning Mask
	0x04	UDINT	x	RW		Manufacturer Warning Mask

Subindex 0x01 (F3A1) Device Warning Mask: Mask bits for 0xF381:01 and 0xF391:01.

Subindex 0x02 (F3A1) Device Warning Mask: Mask bits for 0xF381:02 and 0xF391:02.

Subindex 0x03 (F3A1) Device Warning Mask: Mask bits for 0xF381:03 and 0xF391:03.

Subindex 0x04 (F3A1) Device Warning Mask: Mask bits for 0xF381:04 and 0xF391:04.

Subindex 0x01 (F3A2) Manufacturer Warning Mask: Mask bits for 0xF382:01 and 0xF392:01.

Subindex 0x02 (F3A2) Manufacturer Warning Mask: Mask bits for 0xF382:02 and 0xF392:02.

Subindex 0x03 (F3A2) Manufacturer Warning Mask: Mask bits for 0xF382:03 and 0xF392:03.

Subindex 0x04 (F3A2) Manufacturer Warning Mask: Mask bits for 0xF382:04 and 0xF392:04.

6.6.14 Device Error Mask

Index	SI	DataType	NV	Access	PM	Name
F3A3	0x01	UDINT	x	RW		Device Error Mask
	0x02	UDINT	x	RW		Device Error Mask
	0x03	UDINT	x	RW		Device Error Mask
	0x04	UDINT	x	RW		Device Error Mask
F3A4	0x01	UDINT	x	RW		Manufacturer Error Mask
	0x02	UDINT	x	RW		Manufacturer Error Mask
	0x03	UDINT	x	RW		Manufacturer Error Mask
	0x04	UDINT	x	RW		Manufacturer Error Mask

Subindex 0x01 (F3A3) Device Error Mask: Mask bits for 0xF383:01 and 0xF393:01.

Subindex 0x02 (F3A3) Device Error Mask: Mask bits for 0xF383:02 and 0xF393:02.

Subindex 0x03 (F3A3) Device Error Mask: Mask bits for 0xF383:03 and 0xF393:03.

Subindex 0x04 (F3A3) Device Error Mask: Mask bits for 0xF383:04 and 0xF393:04.

Subindex 0x01 (F3A4) Manufacturer Error Mask: Mask bits for 0xF384:01 and 0xF394:01.

Subindex 0x02 (F3A4) Manufacturer Error Mask: Mask bits for 0xF384:02 and 0xF394:02.

Subindex 0x03 (F3A4) Manufacturer Error Mask: Mask bits for 0xF384:03 and 0xF394:03.

Subindex 0x04 (F3A4) Manufacturer Error Mask: Mask bits for 0xF384:04 and 0xF394:04.

6.6.15 Global Device Warning Mask

Index	SI	DataType	NV	Access	PM	Name
F3A5	0x01	UDINT	x	RW		Global Device Warning Mask
F3A6	0x01	UDINT	x	RW		Global Manufacturer Warning Mask

Subindex 0x01 (F3A5) Global Device Warning Mask: Mask bits for 0xF385:01 and 0xF395:01.

Subindex 0x01 (F3A6) Global Manufacturer Warning Mask: Mask bits for 0xF386:01 and 0xF396:01.

6.6.16 Global Device Error Mask

Index	SI	DataType	NV	Access	PM	Name
F3A7	0x01	UDINT	x	RW		Global Device Error Mask
F3A8	0x01	UDINT	x	RW		Global Manufacturer Error Mask

Subindex 0x01 (F3A7) Global Device Error Mask: Mask bits for 0xF387:01 and 0xF397:01.

Subindex 0x01 (F3A8) Global Manufacturer Error Mask: Mask bits for 0xF388:01 and 0xF398:01.

6.6.17 Combination Gauge

Index	SI	DataType	NV	Access	PM	Name
F640	0x01	BOOL		RO	tx	Combination Gauge Reading Valid
	0x02	BOOL		RO	tx	Combination Gauge Overrange Exceeded
	0x03	BOOL		RO	tx	Combination Gauge Underrange Exceeded
	0x11	REAL		RO	tx	Combination Gauge Active Value
	0x12	UINT		RO	tx	Combination Gauge Active Sensor Number

Subindex 0x01

Identifies whether the complete vacuum pressure gauge (with several measuring principles) is out of its absolute overrange or absolute underrange, or in any other failure condition.

Subindex 0x02

If the bit "Overrange" is set, all modules of the gauge are in an overrange condition.

Subindex 0x03

If the bit "Underrange" is set, all modules of the gauge are in an underrange condition

Subindex 0x11

The value copied from the measurement value of the active measuring module used for the Input PDO.

Subindex 0x12

Identifies the module that is providing the measurement value, the latter of which is copied into the Active Value parameter for all Input PDO's.

0	No module has a valid value
1	Capacitance diaphragm sensor is providing the Active Value
2	Piezo sensor is providing the Active Value
3	Heat Transfer sensor is providing the Active Value
4	Hot Cathode sensor is providing the Active Value

6.6.18 Trip Point Output All

Index	SI	DataType	NV	Access	PM	Name
F641	0x01	UDINT		RO	tx	Trip Point Output All Instance

Subindex 0x01

Status of Trip Point instances.

Trip Point Output All Instance	
Bit 0	Status High Trip (I 0x600E, SI 0x01)
Bit 1	Status Low Trip (I 0x600E S,I 0x02)
Bit 2	Status High Trip (I 0x600F, SI 0x01)
Bit 3	Status Low Trip (I 0x600F, SI 0x02)
Bit 4…31	0

6.6.19 Input Latch Local Timestamp

Index	SI	DataType	NV	Access	PM	Name
F6F0	0x01	UDINT		RO	tx	Input Latch Local Timestamp
	0x02	UDINT		RO	tx	Input Latch Local Timestamp
	0x03	UDINT		RO	tx	Input Latch Local Timestamp
	0x04	UDINT		RO	tx	Input Latch Local Timestamp

Subindex 0x01

Local controller time corresponding to the input latch time in microseconds. It starts at zero on device power-up. Mandatory if device has inputs. If device has no inputs defined, this corresponds the time immediately prior to writing to input SM.

Subindex 0x02

Local controller time corresponding to the input latch time in microseconds. It starts at zero on device power-up. Mandatory if device has inputs. If device has no inputs defined, this corresponds the time immediately prior to writing to input SM.

Subindex 0x03

Local controller time corresponding to the input latch time in microseconds. It starts at zero on device power-up. Mandatory if device has inputs. If device has no inputs defined, this corresponds the time immediately prior to writing to input SM.

Subindex 0x04

Local controller time corresponding to the input latch time in microseconds. It starts at zero on device power-up. Mandatory if device has inputs. If device has no inputs defined, this corresponds the time immediately prior to writing to input SM.

6.6.20 Configure Device

Index	SI	DataType	NV	Access	PM	Name
F840	0x01	UDINT	x	RW		Data Units
	0x03	Enum	x	RW		Data Units Enum

Subindex 0x01

Unit of the Value of the Analog Input Sensor Instance and all related parameters.

Trip Point Output All Instance	
0x00220000	Pascal
0xFD4E0000	mbar
0x00A10000	Torr

If this value is changed, also Subindex 3 will change the value accordingly.

Subindex 0x03

Data Unit for Input Sensor as Enum to have a list of possible values.

Data Units	
0x01(Pa)	Pascal
0x04(mBar)	mbar
0x05(Torr)	Torr

If this value is changed, also Subindex 1 will change the value accordingly.

6.6.21 Information Device

Index	SI	DataType	NV	Access	PM	Name
F940	0x01	UDINT		RO		Measurement Principle
	0x02	BYTE		RO		Number of Sensors
F9F0		V_STRING		RO		Manufacturer Serial Number
F9F1	0x01	UDINT		RO		CDP Functional Generation Number
F9F2	0x01	UDINT		RO		SDP Functional Generation Number (Module 1)
	0x02	UDINT		RO		SDP Functional Generation Number (Module 2)
	0x03	UDINT		RO		SDP Functional Generation Number (Module 3)
	0x04	UDINT		RO		SDP Functional Generation Number (Module 4)
F9F3		V_STRING		RO		Vendor Name
F9F4	0x01	V_STRING		RO		Semiconductor SDP Device Name (Module 1)
	0x02	V_STRING		RO		Semiconductor SDP Device Name (Module 2)
	0x03	V_STRING		RO		Semiconductor SDP Device Name (Module 3)
	0x04	V_STRING		RO		Semiconductor SDP Device Name (Module 4)
F9F5	0x01	USINT		RW	rx tx	Output Identifier
	0x02	USINT		RW	rx tx	Output Identifier
	0x03	USINT		RW	rx tx	Output Identifier
	0x04	USINT		RW	rx tx	Output Identifier
F9F6		UDINT		RO		Time since power on
F9F7		UDINT	x	RO		Total time powered
F9F8		UDINT		RO		Firmware Update Functional Generation Number

Subindex 0x01 (F940)

Measurement principle assigned to the object instance.

The most significant nibble of the parameter represents the sensor type of the first Module, the second most significant nibble of the parameter represents the sensor type of the second Module, and so forth.

Measurement Principle (Index F940)	
1	Capacitance Manometer
2	Piezo
3	Heat Transfer
4	Cold Cathode
5	Hot Cathode

Subindex 0x02 (F940)

Number of Sensors (Index F940): In this device are 4 sensors implemented.

6.6.22 Command Zero Adjust

Execution of this command will start a Zero Adjust operation.

Index	SI	DataType	NV	Access	PM	Name
FB40	0x01	O_STRING		RW		Command
	0x02	BYTE		RO		Status
	0x03	O_STRING(3)		RO		Response

Subindex 0x01

A zero adjust command is initiated when the following byte sequence is sent.

Command	
Byte 0	0: Zero Adjust
Byte 1	Index of the Sensor Module. Value has to be 3 3: Heat Transfer
Byte 2…5	Zero Adjust value (Data format: REAL). Value has to be 0

Subindex 0x02

Status (supported values)	
0	Last command completed, no errors, no reply available
1	Last command completed, no errors, reply available
2	Last command completed, errors present, no reply available
3	Last command completed, errors present, reply available
255	Command is executing

Subindex 0x03

Response	
Byte 0	See Subindex 0x02
Byte 1	not used = 0x00
Byte 2	0: Zero Adjust successful 1: Zero Adjust failed: out-of-range 254: No previous Zero Adjust command issued

6.6.23 Command Full Scale Adjust

Execution of this command will start a Full Scale Adjust operation.

Index	SI	DataType	NV	Access	PM	Name
FB41	0x01	O_STRING		RW		Command
	0x02	BYTE		RO		Status
	0x03	O_STRING(3)		RO		Response

Subindex 0x01

A full scale adjust command is initiated when the following byte sequence is sent.

Command	
Byte 0	0: Full Scale Adjust
Byte 1	Index of the Sensor Module. Value has to be 1 3: Heat Transfer
Byte 2…5	Full Scale value (Data format: REAL). Value has to be 0

Subindex 0x02

Status (supported values)	
0	Last command completed, no errors, no reply available
1	Last command completed, no errors, reply available
2	Last command completed, errors present, no reply available
3	Last command completed, errors present, reply available
255	Command is executing

Subindex 0x03

Response	
Byte 0	See Subindex 0x02
Byte 1	not used = 0x00
Byte 2	0: Full Scale Adjust successful 1: Full Scale Adjust failed: out-of-range 254: No previous Full Scale Adjust command issued

6.6.24 Command Degas ON / OFF

Execution of this command will initiate or cancel a degas operation.

Index	SI	DataType	NV	Access	PM	Name
FB43	0x01	O_STRING(2)		RW		Command
	0x02	BYTE		RO		Status
	0x03	O_STRING(3)		RO		Response

Subindex 0x01

A degas command is initiated when the following byte sequence is sent.

Command	
Byte 0	0: Degas OFF 1: Degas ON
Byte 1	Index of the sensor module. Value has to be 4 4: Hot Cathode

Subindex 0x02

Status (supported values)	
0	Last command completed, no errors, no reply available
1	Last command completed, no errors, reply available
2	Last command completed, errors present, no reply available
3	Last command completed, errors present, reply available
255	Command is executing

Subindex 0x03

Response	
Byte 0	See Subindex 0x02
Byte 1	not used = 0x00
Byte 2	0: Degas ON / OFF successful 1: Degas ON / OFF failed (unspecified reason) 2: Degas On failed because pressure to high 254: No previous Degas ON / OFF command issued

6.6.25 Command Emission ON / OFF

Execution of this command will turn on or off the gauge's emission state.

Index	SI	DataType	NV	Access	PM	Name
FB44	0x01	O_STRING(2)		RW		Command
	0x02	BYTE		RO		Status
	0x03	O_STRING(3)		RO		Response

Subindex 0x01

An emission command is initiated when the following byte sequence is sent.

Command	
Byte 0	0: Emission OFF 1: Emission ON
Byte 1	Index of the sensor module. Value has to be 4 4: Hot Cathode

Subindex 0x02

Status (supported values)	
0	Last command completed, no errors, no reply available
1	Last command completed, no errors, reply available
2	Last command completed, errors present, no reply available
3	Last command completed, errors present, reply available
255	Command is executing

Subindex 0x03

Response	
Byte 0	See Subindex 0x02
Byte 1	not used = 0x00
Byte 2	0: Emission ON / OFF successful 1: Emission ON / OFF failed (unspecified reason) 2: Emission On failed because pressure to high 254: No previous Emission ON / OFF command issued

6.6.26 Device Reset Command

Execution of this command causes the device to emulate a complete power cycle. This includes an ESC reset. An SDP may limit some behavior of the power cycle emulation, but shall not exclude the EtherCAT interface.

As consequence of an ESC reset all following devices are disconnected from the network.

There are two versions of this command:

- Standard reset (as described above).
- Factory reset (as described above, but additionally, all parameters are restored to as-shipped defaults).

Index	SI	DataType	NV	Access	PM	Name
FBF0	0x01	O_STRING(6)		RW		Command
	0x02	BYTE		RO		Status
	0x03	O_STRING(2)		RO		Response

Subindex 0x01

A device reset is initiated when the following byte sequence is sent.

Command	
Byte 0	0x74
Byte 1	0x65
Byte 2	0x73
Byte 3	0x65
Byte 4	0x72
Byte 5	0x00 = Standard reset, 0x66 = Factory Reset

Subindex 0x02

Status (supported values)	
0	Reserved
1	Reserved
2	Last command completed, error, no response
3	Reserved
255	Command is executing

Subindex 0x03

Response	
Byte 0	See Subindex 0x02
Byte 1	not used = 0x00

6.6.27 Exception Reset Command

Execution of this command clears the latched exceptions.

Index	SI	DataType	NV	Access	PM	Name
FBF1	0x01	O_STRING(5)		RW		Command
	0x02	BYTE		RO		Status
	0x03	O_STRING(2)		RO		Response

Subindex 0x01

An exception reset is initiated when the following byte sequence is sent.

Command	
Byte 0	0x74
Byte 1	0x65
Byte 2	0x73
Byte 3	0x65
Byte 4	0x72

Subindex 0x02

Status (supported values)	
0	Last command completed, no error, no response
1	Reserved
2	Last command completed, error, no response
3	Reserved
255	Command is executing

Subindex 0x03

Response	
Byte 0	See Subindex 0x02
Byte 1	not used = 0x00

6.6.28 Store Parameters Command

Execution of this command will store all parameters to non-volatile memory. If a device automatically saves all non-volatile parameters at the time they are set, this command will not take any action.

Index	SI	DataType	NV	Access	PM	Name
FBF2	0x01	O_STRING(4)		RW		Command
	0x02	BYTE		RO		Status
	0x03	O_STRING(2)		RO		Response

Subindex 0x01

A device reset is initiated when the following byte sequence is sent.

Read:

Command: Read	
Byte 0	0x01 = slave saves the non-volatile parameters when writing 0xFBF2:01 with 0x65766173
Byte 1	not used = 0x00
Byte 2	not used = 0x00
Byte 3	not used = 0x00

Write:

Command: Write	
Byte 0	0x73
Byte 1	0x61
Byte 2	0x76
Byte 3	0x65

Subindex 0x02

Status (supported values)	
0	Last command completed, no error, no response
1	Reserved
2	Last command completed, error, no response
3	Reserved
255	Command is executing

Subindex 0x03

Response	
Byte 0	See Subindex 0x02
Byte 1	not used = 0x00

6.6.29 Calculate Checksum Command

Execution of this command will calculate a checksum for all writable, non-volatile parameters as currently stored in non-volatile memory.

Index	SI	DataType	NV	Access	PM	Name
FBF3	0x01	O_STRING(4)		RW		Command
	0x02	BYTE		RO		Status
	0x03	O_STRING(6)		RO		Response

Subindex 0x01

A device reset is initiated when the following byte sequence is sent.

Read

Command: Read	
Byte 0	Bit 0 = 1: non-volatile parameters supported Bit 1 = 1: CRC-32 Bit 2..7 = 0: not used
Byte 1	not used = 0x00
Byte 2	not used = 0x00
Byte 3	not used = 0x00

Write

Command: Write	
Byte 0	Bit 0 = 1: use default checksum algorithm of the slave Bit 1 = 1: CRC-32 Bit 2..7 = 0: not used
Byte 1	not used = 0x00
Byte 2	not used = 0x00
Byte 3	not used = 0x00

Subindex 0x02

Status (supported values)	
0	Last command completed, no error, no response
1	Reserved
2	Last command completed, error, no response
3	Reserved
255	Command is executing

Subindex 0x03

Response	
Byte 0	See Subindex 0x02
Byte 1	not used = 0
Byte 2	Checksum return value, Byte 0
Byte 3	Checksum return value, Byte 1
Byte 4	Checksum return value, Byte 2
Byte 5	Checksum return value, Byte 3

6.6.30 Load Parameters Command

Execution of this command will load all parameters from non-volatile memory.

Index	SI	DataType	NV	Access	PM	Name
FBF4	0x01	O_STRING(4)		RW		Command
	0x02	BYTE		RO		Status
	0x03	O_STRING(2)		RO		Response

Subindex 0x01

A device reset is initiated when the following byte sequence is sent.

Read:

Command: Read	
Byte 0	0x01 = slave loads the non-volatile parameters when writing 0xFBF4:01 with 0x64616F6C
Byte 1	not used = 0x00
Byte 2	not used = 0x00
Byte 3	not used = 0x00

Write:

Command: Write	
Byte 0	0x6C
Byte 1	0x6F
Byte 2	0x61
Byte 3	0x64

Subindex 0x02

Status (supported values)	
0	Last command completed, no error, no response
1	Reserved
2	Last command completed, error, no response
3	Reserved
255	Command is executing

Subindex 0x03

Response	
Byte 0	See Subindex 0x02
Byte 1	not used = 0x00

Appendix

A: Overview Setting Trip Points

Input Data Trip Point

Index	Object Code	Sub Index	Data Type	Ac-cess	B/S	PM	Name	Description
0x6nnx	RECORD			RO			Input Trip Point 1 / 2	Trip Point 1 / Trip Point 2 E = Trip Point 1 F = Trip Point 2
0x600E 0x600F		0x01	BOOL	RO		tx	Status High Trip	1: High Trip asserted
0x600E 0x600F		0x02	BOOL	RO		tx	Status Low Trip	2: Low Trip asserted

Trip Point 1		Trip Point 2	
BAG552	→ 14	BAG552	→ 14
BPG552	→ 34	BPG552	→ 34
BCG552	→ 60	BCG552	→ 60

Trip Point Configuration

Index	Object Code	Sub Index	Data Type	Ac-cess	B/S	PM	Name	Description
0x8nnx	RECORD			RO			Configuration Trip Point 1 / 2	Trip Point 1 / 2 E = Trip Point 1 F = Trip Point 2
0x800E 0x800F		0x01	BOOL	RW	B/S		High Trip enable	High Trip Point 0: disable 1: enable
0x800E 0x800F		0x02	BOOL	RW	B/S		Low Trip enable	Low Trip Point 0: disable 1: enable
0x800E 0x800F		0x11	REAL	RW	B/S		High Trip Point Limit	Mandatory, if 0x8nnE.20 is not supported (Low Trip Point Limit). High limit to trigger trip point condition, if Input Value (I 0x9nnE, SI 0x01) is above this limit.
0x800E 0x800F		0x12	UDINT	RW	B/S		High Trip Source Index	Object index of High Trip Point Value source. Bit 16…31: Index Bit 08…15: Subindex Bit 00…07: reserved It is possible to reference to "High Trip Point Limit" or any other available input source from another sensor (in case of combi / multigauge; BCG552).
0x800E 0x800F		0x13	REAL	RW	B/S		Percentage High Trip Source	Percentage of value referenced by High Trip Source Index (I 0x8nnE, SI 0x12) in %.
0x800E 0x800F		0x14	REAL	RW	B/S		Low Trip Point Limit	Mandatory, if 0x8nnE.17 is not supported (High Trip Point Limit). Low limit to trigger trip point condition, if Input Value (I 0x9nnE, SI 0x01) is below this limit.

(continued)

(Table "Trip Point Configuration" concluded)

Index	Object Code	Sub Index	Data Type	Ac-cess	B/S	PM	Name	Description
0x800E 0x800F		0x15	UDINT	RW	B/S		Low Trip Source Index	Object index of Low Trip Point Value source. Bit 16…31: Index Bit 08…15: Subindex Bit 00…07: reserved It is possible to reference to "Low Trip Point Limit" or any other available input source from another sensor (in case of combi / multigauge; BCG552).
0x800E 0x800F		0x16	REAL	RW	B/S		Percentage Low Trip Source	Percentage of value referenced by Low Trip Source Index (I 0x8nnE, SI 0x15) in %.
0x800E 0x800F		0x17	REAL	RW	B/S		High Trip Hysteresis	Mandatory, if 0x8nnE.17 is not supported (High Trip Point Limit). Hysteresis value for High Trip Point.
0x800E 0x800F		0x18	REAL	RW	B/S		Low Trip Hysteresis	Mandatory, if 0x8nnE.20 is not supported (Low Trip Point Limit). Hysteresis value for Low Trip Point.
0x800E 0x800F		0x1A	UDINT	RW	B/S		Source Index	Mandatory, if combi and multigauges and High Trip Point Limit or Low Trip Point Limit supported. Object index of active source of Input Value (I 0x9nnE, SI 0x01). Bit 16…31: Index Bit 08…15: Subindex Bit 00…07: reserved

Trip Point 1

BAG552	→ 15
BPG552	→ 35
BCG552	→ 61

Trip Point 2

BAG552	→ 17
BPG552	→ 37
BCG552	→ 63

Information Data of the Modules

Index	Object Code	Sub Index	Data Type	Ac-cess	B/S	PM	Name	Description
0x9nnx	RECORD			RO			Information Trip Point 1 / 2	Trip Point 1 / Trip Point 2 E = Trip Point 1 F = Trip Point 2
0x900E 0x900F		0x01	REAL	RO			Input Value of Trip Point 1 / 2	Mandatory, if 0x8nnE.26 is not supported (Source Index). Trip Point Input value as referenced by Source Index (I 0x8nnE, SI 0x1A).

Trip Point 1 / 2

BAG552	→ 19
BPG552	→ 39
BCG552	→ 65

Trip Point All Slots Combined

Index	Object Code	Sub Index	Data Type	Access	B/S	PM	Name	Description
0xF641	RECORD			RO			Trip Point Output All	Trip Point Output All
0xF641		0x01	UDINT	RO		TX	Trip Point Output All Instance	Status of Trip Point Instances Bit 0: Status High Trip (I 0x6nnE, SI 0x01) Bit 1: Status Low Trip (I 0x6nnE, SI 0x02) Bit 2: Status High Trip (I 0x6nnF, SI 0x01) Bit 3: Status Low Trip (I 0x6nnF, SI 0x02)

Trip Point 1 / 2

BAG552 → 23
BPG552 → 45
BCG552 → 74

B: Examples Setting Trip Points

Setting SP1 (Low Trip Point)

Setting a low trip point for the first trip point with a limit value of 5.500E-03 and a hysteresis of 10% (5.500E-4) of the limit value.

The configured trip point is active if the pressure is lower than 5.500E-03. It is inactive if the pressure is higher than 6.050E-3.

Trip Point Configuration

Index	Object Code	Sub Index	Data Type	Access	B/S	PM	Name	Description
0x8nnE	RECORD			RO			Configuration Trip Point 1	Trip Point 1 E = Trip Point 1
0x800E		0x02	BOOL	RW	B/S		Low Trip enable	Low Trip Point **1: enable**
0x800E		0x14	REAL	RW	B/S		Low Trip Point Limit	Low limit to trigger trip point condition, if Input Value (I 0x9nnE, SI 0x01) is below this limit. **Write Value: 5.5E-3**
0x800E		0x15	UDINT	RW	B/S		Low Trip Source Index	Object index of Low Trip Point Value source. Bit 16…31: Index Bit 08…15: Subindex Bit 00…07: reserved It is possible to reference to "Low Trip Point Limit" or any other available input source from another sensor (in case of combi / multigauge; BCG552). **Has to be 0x800E1400**
0x800E		0x18	REAL	RW	B/S		Low Trip Hysteresis	Hysteresis value for Low Trip Point. **Write Value: 5.5E-4**
0x800E		0x1A	UDINT	RW	B/S		Source Index	Object index of active source of Input Value (I 0x9nnE, SI 0x01). Bit 16…31: Index Bit 08…15: Subindex Bit 00…07: reserved **Has to be 0xF6401100**

Setting SP2 (High Trip Point)

Setting a high trip point for the second trip point with a limit value of 5.500E-03 and a hysteresis of 10% (5.500E-4) of the limit value.

The configured trip point is active if the pressure is higher than 5.500E-03. It is inactive if the pressure is higher than 4.9500E-3.

Trip Point Configuration

Index	Object Code	Sub Index	Data Type	Ac-cess	B/S	PM	Name	Description
0x8nnF	RECORD			RO			Configuration Trip Point 2	Trip Point 2 F = Trip Point 2
0x800F		0x01	BOOL	RW	B/S		High Trip enable	High Trip Point **1: enable**
0x800F		0x11	REAL	RW	B/S		High Trip Point Limit	High limit to trigger trip point condition, if Input Value (I 0x9nnE, SI 0x01) is above this limit. **Write Value: 5.5E-3**
0x800F		0x12	UDINT	RW	B/S		High Trip Source Index	Object index of High Trip Point Value source. Bit 16…31: Index Bit 08…15: Subindex Bit 00…07: reserved It is possible to reference to "High Trip Point Limit" or any other available input source from another sensor (in case of combi / multigauge; BCG552). **Has to be 0x800F1100**
0x800F		0x13	REAL	RW	B/S		Percentage High Trip Source	Percentage of value referenced by High Trip Source Index (I 0x8nnE, SI 0x12) in %. **Not used**
0x800F		0x17	REAL	RW	B/S		High Trip Hysteresis	Mandatory, if 0x8nnE.17 is not supported (High Trip Point Limit). Hysteresis value for High Trip Point. **Write Value: 5.5E-4**
0x800F		0x1A	UDINT	RW	B/S		Source Index	Object index of active source of Input Value (I 0x9nnE, SI 0x01). Bit 16…31: Index Bit 08…15: Subindex Bit 00…07: reserved **Has to be 0xF6401100**

Setting ATM sensor (SP1, High Trip Point)

BCG552 only.

An atmosphere high trip point at 90% of atmosphere pressure, will be set using percentage of the atmosphere sensor. The hysteresis is set to 20 mbar.

Assumption that the atmosphere pressure is 950 mbar: The set point will be active if the pressure is at 855 mbar (=0.9×950 mbar) or higher. If the pressure is below 835 mbar the setpoint is inactive.

Trip Point Configuration

Index	Object Code	Sub Index	Data Type	Ac-cess	B/S	PM	Name	Description
0x8nnE	RECORD			RO			Configuration Trip Point 1	Trip Point 1 / 2 E = Trip Point 1
0x800E		0x01	BOOL	RW	B/S		High Trip enable	High Trip Point **1: enable**
0x800E		0x11	REAL	RW	B/S		High Trip Point Limit	High limit to trigger trip point condition, if Input Value (I 0x9nnE, SI 0x01) is above this limit. **Not used**
0x800E		0x12	UDINT	RW	B/S		High Trip Source Index	Object index of High Trip Point Value source. Bit 16…31: Index Bit 08…15: Subindex Bit 00…07: reserved It is possible to reference to "High Trip Point Limit" or any other available input source from another sensor (in case of combi / multigauge; BCG552). **Has to be 0x60101100**
0x800E		0x13	REAL	RW	B/S		Percentage High Trip Source	Percentage of value referenced by High Trip Source Index (I 0x8nnE, SI 0x12) in %. **Write Value: 90.0**
0x800E		0x17	REAL	RW	B/S		High Trip Hysteresis	Mandatory, if 0x8nnE.17 is not supported (High Trip Point Limit). Hysteresis value for High Trip Point. **Write Value: 20**
0x800E		0x1A	UDINT	RW	B/S		Source Index	Mandatory, if combi and multigauges and High Trip Point Limit or Low Trip Point Limit supported. Object index of active source of Input Value (I 0x9nnE, SI 0x01). Bit 16…31: Index Bit 08…15: Subindex Bit 00…07: reserved **Has to be 0xF6401100**

C: Literature

🕮 [1] Operating Manual
Trigon™ BAG552
Bayard-Alpert Pirani SingleGauge
tinb87e1 (English)
INFICON AG, LI–9496 Balzers, Liechtenstein

🕮 [2] Operating Manual
Trigon™ BPG552
Bayard-Alpert Pirani DualGauge
tinb80e1 (English)
INFICON AG, LI–9496 Balzers, Liechtenstein

🕮 [3] Operating Manual
Trigon™ BCG552
Bayard-Alpert Pirani Capacitance Diaphragm TripleGauge®
tinb77e1 (English)
INFICON AG, LI–9496 Balzers, Liechtenstein

🕮 [4] ETG.1000.2: Physical Layer service definition and protocol specification

🕮 [5] ETG.1000.3: Data Link Layer service definition

🕮 [6] ETG.1000.4: Data Link Layer protocol specification

🕮 [7] ETG.1000.5: Application Layer service definition

🕮 [8] ETG.1000.6: Application Layer protocol specification

🕮 [9] ETG.1020: EtherCAT Protocol Enhancements

🕮 [10] ETG.2000: EtherCAT Slave Information

🕮 [11] ETG.5001.1: Modular Device Profile – Part 1: General MDP Device Model

🕮 [12] ETG.5003.1 S (R) V1.1.0: Semiconductor Device profile – Part 1: Common Device Profile (CDP)

🕮 [13] ETG.5003.2080 S (R) V1.3.0: Semiconductor Device profile – Part 2080: Specific Device Profile (SDP): Vacuum Pressure Gauge

🕮 [14] IEC 61158-x-12 (all parts for type 12): Industrial communication networks – Fieldbus specifications

🕮 [15] IEC 61784-2: Industrial communication networks – Profiles – Part 2: Additional fieldbus profiles for real-time networks based on ISO/IEC 8802-3

🕮 [16] SEMI E54 / Draft 5102A: SPECIFICATION FOR SENSOR/ACTUATOR NETWORK SPECIFIC DEVICE MODEL FOR VACUUM PRESSURE GAUGES

🕮 [17] SEMI E52: Practice for referencing gases, gas mixtures and vaporizable materials used in digital mass flow controllers

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